

# Additional Material (Lab3-1)

## Create your network

### Time Delay Neural Network

#### IDNN in the lectures

```
net = timedelaynet(inputDelays,hiddenSizes,trainFcn)
```

|             |   |
|-------------|---|
| inputDelays | Row vector of increasing 0 or positive delays (default = 1:2) |
| hiddenSizes | Row vector of one or more hidden layer sizes (default = 10)   |
| trainFcn    | Training function (default = 'trainlm')                       |

Note: for input delays standard dependencies from present input are represented by a 0 delay. Thereby, use inputDelays = 0:4 for an input window of size 5 that spans from the present input to the input 5 steps before.

### Layer Recurrent Neural Network (RNNs)

#### SRN with BPTT in the lectures

```
net = layrecnet(layerDelays,hiddenSizes,trainFcn)
```

|             |   |
|-------------|---|
| layerDelays | Row vector of increasing positive delays (default = 1:2) – <u>use layerDelays = 1</u> |
| hiddenSizes | Row vector of one or more hidden layer sizes (default = 10)                           |
| trainFcn    | Training function (default = 'trainlm')   |

Note: delays corresponding to feedback connections should be >0.

## Nonlinear autoregressive with exogenous inputs (NARX)

```
net = narxnet(inputDelays,feedbackDelays,hiddenSizes,trainFcn)
```

|                       |   |
|-----------------------|---|
| <b>inputDelays</b>    | Row vector of increasing 0 or positive delays (default = 1:2) |
| <b>feedbackDelays</b> | Row vector of increasing 0 or positive delays (default = 1:2) |
| <b>hiddenSizes</b>    | Row vector of one or more hidden layer sizes (default = 10)   |
| <b>trainFcn</b>       | Training function (default = 'trainlm')                       |

Note: the network should be trained and used in closeloop form.

In older versions of Matlab you should set it using the command, i.e.

```
net = closeloop(net)
```

From 2016a version of Matlab you need to specify the openloop or closeloop option as a feedback mode when you create the NARX network, according to the following:

```
net = narxnet(inputDelays,feedbackDelays,hiddenSizes, feedbackMode,trainFcn)
```

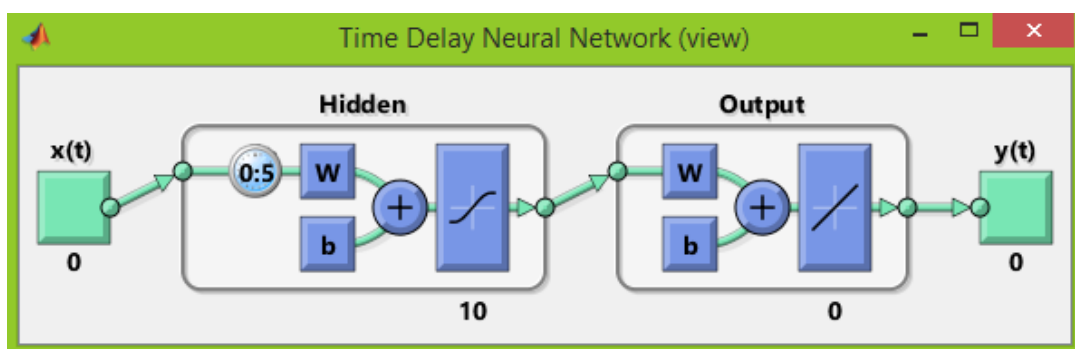
|                       |   |
|-----------------------|---|
| <b>inputDelays</b>    | Row vector of increasing 0 or positive delays (default = 1:2) |
| <b>feedbackDelays</b> | Row vector of increasing 0 or positive delays (default = 1:2) |
| <b>hiddenSizes</b>    | Row vector of one or more hidden layer sizes (default = 10)   |
| <b>feedbackMode</b>   | An 'open' or 'closed' feedback mode                           |
| <b>trainFcn</b>       | Training function (default = 'trainlm')                       |

# Customize your network

- Sizes of hidden layers, e.g.  
`net.layers{1}.size = 30;`
- Training function (weight update rule), e.g.  
`net.trainFcn = 'traingd'; %gradient descent`  
`net.trainFcn = 'traingdm'; %gradient descent with momentum`  
`net.trainFcn = 'traingdx'; %gradient descent with momentum and adaptive %learning rate`  
`net.trainFcn = 'trainrp'; %rprop`  
`net.trainFcn = 'trainlm'; %Levenberg-Marquardt optimization`
- Training parameters, e.g.  
`net.trainParam.lr = 0.001; %learning rate for gradient descent alg.`  
`net.trainParam.mc = 0.5; %momentum constant`  
`net.trainParam.epochs = 1000; %maximum number of epochs`
- Regularization, e.g.  
`net.performParam.regularization = 0.1; %for weight decay regularization`
- Data splitting (divide function), e.g.  
`net.divideFcn = 'dividerand'; %automatic split in tr, vl, ts sets %not recommended!`  
`net.divideFcn = 'dividetrain'; %all samples provided with train command %are used for training`

View your network's architecture using the command:

`view(net)`



# Prepare the (time series) input for your network

## preparets

---

Prepare input and target time series data for network simulation or training

### Syntax

---

```
[Xs,Xi,Ai,Ts,EWs,shift] = preparets(net,Xnf,Tnf,Tf,EW)
```

Input:

|     |                               |
|-----|-------------------------------|
| net | Neural network                |
| Xnf | Non-feedback inputs           |
| Tnf | Non-feedback targets          |
| Tf  | Feedback targets              |
| EW  | Error weights (default = {1}) |

Output:

|       |  |
|-------|--|
| Xs    | Shifted inputs   |
| Xi    | Initial input delay states   |
| Ai    | Initial layer delay states   |
| Ts    | Shifted targets  |
| EWs   | Shifted error weights  |
| shift | The number of timesteps truncated from the front of X and T in order to properly fill Xi and Ai. |

e.g.

```
[delayedInput, initialInput, initialStates, delayedTarget] = preparets(net,  
input, target)
```

# Train your network

## train

Train neural network

[collapse all in page](#)

### Syntax

```
[net,tr] = train(net,X,T,Xi,Ai,EW)
```

Input:

|     |  |
|-----|--|
| net | Network  |
| X   | Network inputs                                   |
| T   | Network targets (default = zeros)                |
| Xi  | Initial input delay conditions (default = zeros) |
| Ai  | Initial layer delay conditions (default = zeros) |
| EW  | Error weights                                    |

Output:

|     |                                  |
|-----|----------------------------------|
| net | Newly trained network            |
| tr  | Training record (epoch and perf) |

e.g.

```
[net,tr] = train(net, delayedInput, delayedTarget, initialInput); %for time delay  
neural networks
```

Note: net and tr are two of the structures that you have to include in your assignment output.