Overview

Introduction

Modelling parallel systems

Linear Time Properties

Regular Properties

Linear Temporal Logic (LTL)

Computation Tree Logic

- syntax and semantics of CTL
- expressiveness of CTL and LTL
- CTL model checking ⟵
- fairness, counterexamples/witnesses
- CTL^+ and CTL^*

Equivalences and Abstraction

CTL model checking

given: finite TS $\mathcal{T} = (S, Act, \rightarrow, S_0, AP, L)$
CTL formula Φ over AP

question: does $\mathcal{T} \models \Phi$ hold **?**

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idea:

- compute $Sat(\Phi) = \{s \in S : s \models \Phi\}$
- check whether $S_0 \subseteq Sat(\Phi)$

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```
FOR ALL subformulas Ψ of Φ DO
    compute Sat(Ψ)

OD
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FOR ALL subformulas Ψ of Φ DO
    compute Sat(Ψ)
    replace Ψ by a new atomic proposition a_Ψ
    FOR ALL s ∈ Sat(Ψ) DO add a_Ψ to L(s) OD
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OD
IF S_0 ⊆ Sat(Φ) THEN output "yes"
                ELSE output "no"
FI
```

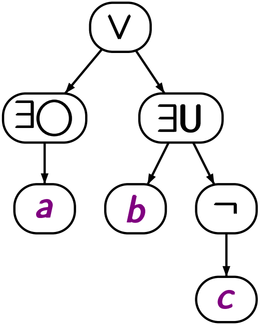
Example: CTL model checking

$$\Phi = \exists \bigcirc a \lor \exists (b \, \mathsf{U} \, \neg c)$$

Example: CTL model checking

$$\Phi = \exists \bigcirc a \ \vee \exists (b \, \mathsf{U} \, \neg c)$$

syntax tree for Φ



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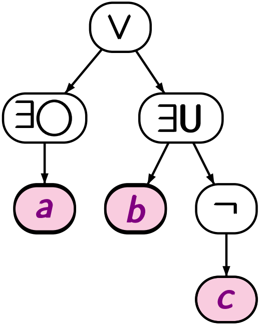

processed in bottom-up fashion

compute $Sat(a), Sat(b), Sat(c)$

Example: CTL model checking

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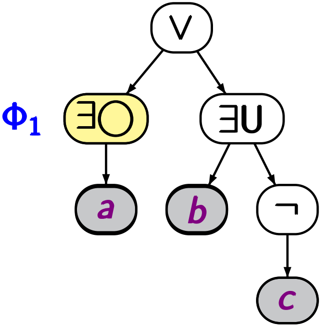

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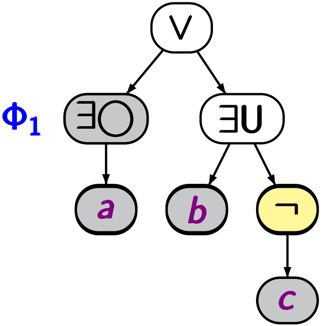

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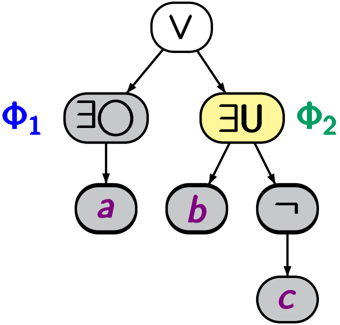
Example: CTL model checking

$$\Phi = \underbrace{\exists\bigcirc a}_{\Phi_1} \vee \underbrace{\exists(b \,\mathsf{U}\, \neg c)}_{\Phi_2}$$

syntax tree for Φ



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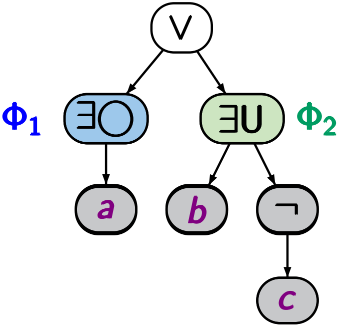

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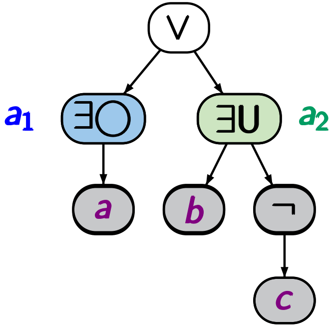
replace Φ_1 with a_1

replace Φ_2 with a_2

Example: CTL model checking

$$\Phi = \underbrace{\exists\bigcirc a}_{\Phi_1} \vee \underbrace{\exists(b \,\mathsf{U}\, \neg c)}_{\Phi_2} \quad \rightsquigarrow \quad a_1 \vee a_2$$

syntax tree for Φ



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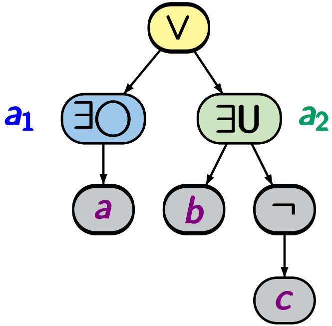
syntax tree for Φ



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$Sat(\Phi_1) = \ldots = Sat(a_1)$

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$Sat(\Phi_2) = \ldots = Sat(a_2)$

replace Φ_1 with a_1
replace Φ_2 with a_2

$Sat(\Phi) = Sat(a_1) \cup Sat(a_2)$

CTL model checking

given: finite TS $\mathcal{T} = (S, Act, \rightarrow, S_0, AP, L)$
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method: regard in bottom-up manner all subformulas Ψ of Φ and compute their satisfaction sets

$$Sat(\Psi) = \{s \in S : s \models \Psi\}$$

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here: explanations for the case that Φ is in existential normal form

analogous algorithms can be designed for standard CTL (and the derived operators)

Recall: Existential normal form for CTL

For each **CTL** formula there is an equivalent formula in **∃-normal form**, i.e., a **CTL** formula with the basis modalities $\exists\bigcirc$, $\exists\mathbf{U}$, $\exists\Box$.

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CTL formulas in ∃-normal form:

$$\Psi \;::=\; \mathit{true} \mid a \mid \neg\Psi \mid \Psi_1 \wedge \Psi_2 \mid$$
$$\exists\bigcirc\Psi \mid \exists(\Psi_1 \,\mathsf{U}\, \Psi_2) \mid \exists\Box\Psi$$

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$$\Psi \ ::= \ \mathit{true} \mid a \mid \neg\Psi \mid \Psi_1 \wedge \Psi_2 \mid \exists\bigcirc\Psi \mid \exists(\Psi_1 \,\mathsf{U}\, \Psi_2) \mid \exists\Box\Psi$$

CTL formula $\rightsquigarrow$ **CTL** formula in ∃-normal form

$$\forall\bigcirc\Phi \rightsquigarrow \neg\exists\bigcirc\neg\Phi$$

$$\forall(\Phi_1 \,\mathsf{U}\, \Phi_2) \rightsquigarrow \neg\exists(\neg\Phi_2 \,\mathsf{U}(\neg\Phi_1 \wedge \neg\Phi_2)) \wedge \neg\exists\Box\neg\Phi_2$$

Recursive computation of the satisfaction sets

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$$Sat(true) = S$$

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\begin{aligned}
Sat(true) &= S \\
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Sat(\neg\Phi) &= S \setminus Sat(\Phi)
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Sat(\exists(\Phi_1 \,\mathsf{U}\, \Phi_2)) &= \ \ldots \\
Sat(\exists\Box\Phi) &= \ \ldots
\end{aligned}
$$

treatment of $\exists\mathsf{U}$ and $\exists\Box$:

via fixed point computation

Recall: expansion law for ∃U

$$\exists(\Phi_1 \, \mathsf{U} \, \Phi_2) \;\equiv\; \Phi_2 \vee \big(\Phi_1 \wedge \exists\bigcirc\exists(\Phi_1 \, \mathsf{U} \, \Phi_2)\big)$$

Recall: expansion law for $\exists U$

$$\exists(\Phi_1 \, U \, \Phi_2) \;\equiv\; \Phi_2 \vee \big(\Phi_1 \wedge \exists\bigcirc\exists(\Phi_1 \, U \, \Phi_2)\big)$$

$$Sat(\exists(\Phi_1 \, U \, \Phi_2)) = Sat(\Phi_2) \cup$$
$$\big\{ s \in Sat(\Phi_1) : Post(s) \cap Sat(\exists(\Phi_1 \, U \, \Phi_2)) \neq \varnothing \big\}$$

Fixed point characterization of ∃U

$$\exists(\Phi_1 \,\mathsf{U}\, \Phi_2) \;\equiv\; \Phi_2 \vee \big(\Phi_1 \wedge \exists\bigcirc\exists(\Phi_1 \,\mathsf{U}\, \Phi_2)\big)$$

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i.e., the set $T = Sat(\exists(\Phi_1 \,\mathsf{U}\, \Phi_2))$ is a **fixed point** of the higher-order function $\Omega : 2^S \to 2^S$ given by:

$$\Omega(T) \;=\; Sat(\Phi_2) \cup \big\{ s \in Sat(\Phi_1) : Post(s) \cap T \neq \varnothing \big\}$$

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satisfies the following conditions:

(1) $Sat(\Phi_2) \subseteq Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$

(2) If $s \in Sat(\Phi_1)$ and $Post(s) \cap Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2)) \neq \varnothing$
then $s \in Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$

Least fixed point characterization of ∃U

$$\exists(\Phi_1 \,\mathsf{U}\, \Phi_2) \;\equiv\; \Phi_2 \vee \big(\Phi_1 \wedge \exists\bigcirc\exists(\Phi_1 \,\mathsf{U}\, \Phi_2)\big)$$

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satisfies the following conditions:

(1) $Sat(\Phi_2) \subseteq Sat(\exists(\Phi_1 \,\mathsf{U}\, \Phi_2))$

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$Sat(\exists(\Phi_1 \mathsf{U} \Phi_2))$ is the smallest set s.t. (1) and (2) hold

The always operator

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$$Sat(\exists\Box\Phi) = \text{greatest set } V \text{ of states s.t.}$$

$$V \subseteq \{ s \in Sat(\Phi) : Post(s) \cap V \neq \varnothing \}$$

Greatest fixed point characterization of $\exists\Box$

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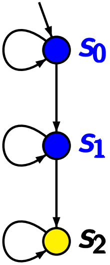

Greatest fixed point characterization of $\exists\Box$

$Sat(\exists\Box\Phi)$ = greatest set V of states s.t.

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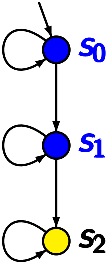

$V = \{s_0\}$ satisfies (*)

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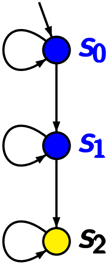

$V = \{s_0\}$ satisfies (*)

$V \subsetneq Sat(\exists\Box a) = \{s_0, s_1\}$

Until versus weak until

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The formulas $\Psi = \exists(\Phi_1 \mathsf{U} \Phi_2)$ and $\Psi = \exists(\Phi_1 \mathsf{W} \Phi_2)$ fulfill the expansion law

$$\Psi \equiv \Phi_2 \vee (\Phi_1 \wedge \exists \bigcirc \Psi)$$

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until: $Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2)) =$ smallest set T of states s.t.

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weak until: $Sat(\exists(\Phi_1 \, \mathsf{W} \, \Phi_2))$ = greatest set V s.t.

$$Sat(\Phi_2) \cup \{ s \in Sat(\Phi_1) : Post(s) \cap V \neq \varnothing \} \supseteq V$$

Fixed point equations for $\exists$U

$Sat(\exists(a \,\mathsf{U}\, b))$ = smallest set of states T s.t.

$$(*) \quad Sat(b) \cup \{ s \in Sat(a) : Post(s) \cap T \neq \varnothing \} \subseteq T$$

Fixed point equations for ∃U

$Sat(\exists(a \, \mathsf{U} \, b))$ = smallest set of states T s.t.

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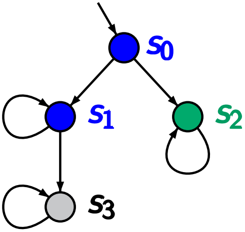

Fixed point equations for ∃U and ∃W

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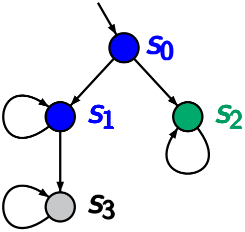

$T = \{s_0, s_1, s_2\}$ satisfies $(*)$

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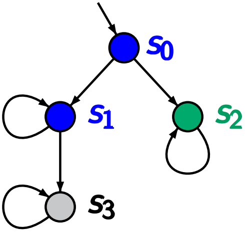

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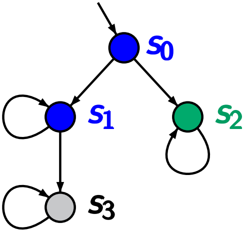
$Sat(\exists(a \, \mathsf{W} \, b))$ = greatest set of states V s.t.

$$(**) \quad V \subseteq Sat(b) \cup \{s \in Sat(a) : Post(s) \cap V \neq \varnothing\}$$



$T = \{s_0, s_1, s_2\}$ satisfies $(*)$

$Sat(\exists(a \, \mathsf{U} \, b)) = \{s_0, s_2\} \subsetneq T$

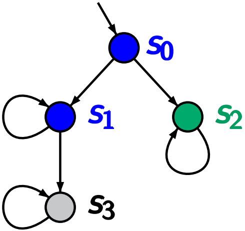
Fixed point equations for $\exists U$ and $\exists W$

$Sat(\exists(a \, \mathsf{U} \, b))$ = smallest set of states T s.t.

$$(*) \quad Sat(b) \cup \{s \in Sat(a) : Post(s) \cap T \neq \varnothing\} \subseteq T$$

$Sat(\exists(a \, \mathsf{W} \, b))$ = greatest set of states V s.t.

$$(**) \quad V \subseteq Sat(b) \cup \{s \in Sat(a) : Post(s) \cap V \neq \varnothing\}$$



$T = \{s_0, s_1, s_2\}$ satisfies $(*)$

$Sat(\exists(a \, \mathsf{U} \, b)) = \{s_0, s_2\} \subsetneq T$

$V = \{s_0, s_2\}$ satisfies $(**)$

Fixed point equations for ∃U and ∃W

$Sat(\exists(a \,\mathsf{U}\, b))$ = smallest set of states T s.t.

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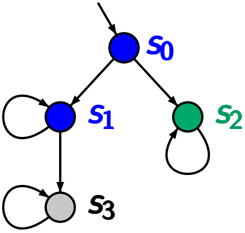
$Sat(\exists(a \,\mathsf{W}\, b))$ = greatest set of states V s.t.

$$(**) \quad V \subseteq Sat(b) \cup \{ s \in Sat(a) : Post(s) \cap V \neq \varnothing \}$$



$T = \{s_0, s_1, s_2\}$ satisfies $(*)$

$Sat(\exists(a \,\mathsf{U}\, b)) = \{s_0, s_2\} \subsetneq T$

$V = \{s_0, s_2\}$ satisfies $(**)$, but

$V \subsetneq Sat(\exists(a \,\mathsf{W}\, b)) = \{s_0, s_1, s_2\}$

Universally quantified formulas

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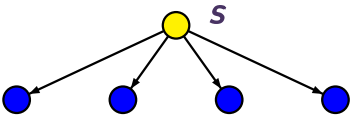
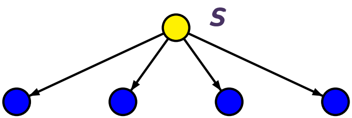


Universally quantified formulas

$$Sat(\forall \bigcirc a) = \{ s \in S : Post(s) \subseteq Sat(a) \}$$



$Sat(\forall \Box a) =$ greatest set T of states s.t.

$$T \subseteq \{ s \in Sat(a) : Post(s) \subseteq T \}$$

Universally quantified formulas

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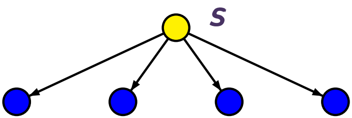

$Sat(\forall \Box a)$ = greatest set T of states s.t.

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$Sat(\forall (a \, \mathsf{U} \, b))$ = smallest set T of states s.t.

$$Sat(b) \cup \{ s \in Sat(a) : Post(s) \subseteq T \} \subseteq T$$

Recursive computation of *Sat*(...)

$$Sat(\Phi_1 \wedge \Phi_2) = Sat(\Phi_1) \cap Sat(\Phi_2)$$

$$Sat(\neg\Phi) = S \setminus Sat(\Phi)$$

$$Sat(\exists\bigcirc\Phi) = \{s \in S : Post(s) \cap Sat(\Phi) = \varnothing\}$$

$Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$ = smallest set T of states s.t.

- $Sat(\Phi_2) \subseteq T$
- $s \in Sat(\Phi_1)$ and $Post(s) \cap T \neq \varnothing \implies s \in T$

$Sat(\exists\Box\Phi)$ = greatest set V of states s.t.

- $V \subseteq Sat(\Phi)$
- $s \in V \implies Post(s) \cap V \neq \varnothing$

CTL model checking: until operator

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$$\exists(\Phi_1 \,\mathsf{U}\, \Phi_2) \;\equiv\; \Phi_2 \vee (\Phi_1 \wedge \exists\bigcirc\exists(\Phi_1 \,\mathsf{U}\, \Phi_2))$$

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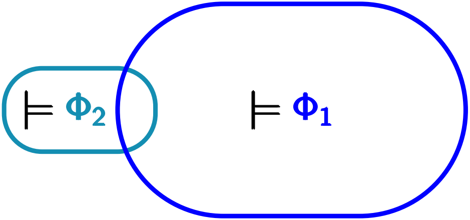

$T_0 := Sat(\Phi_2)$

CTL model checking: until operator

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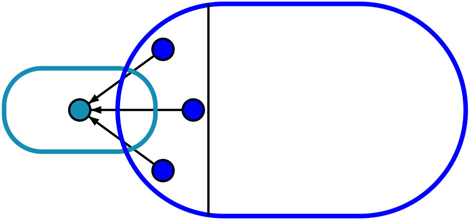

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CTL model checking: until operator

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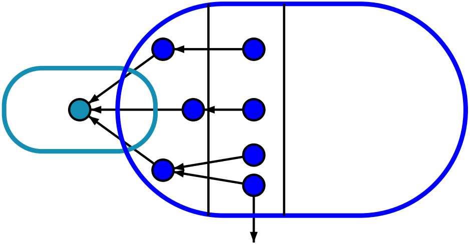

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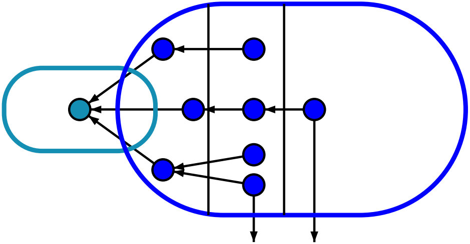

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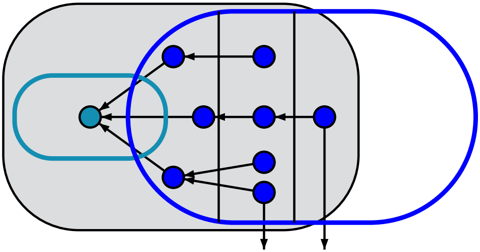

$Sat(\exists(\Phi_1 \,\mathsf{U}\, \Phi_2))$

CTL model checking: until operator

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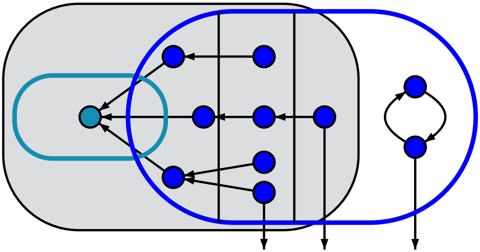
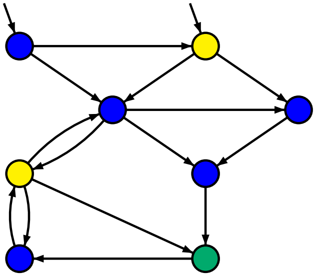


$Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$

Example: until operator

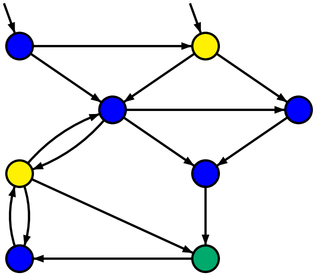


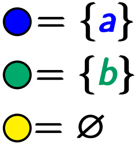
(blue) $= \{a\}$

(green) $= \{b\}$

(yellow) $= \varnothing$

Example: until operator





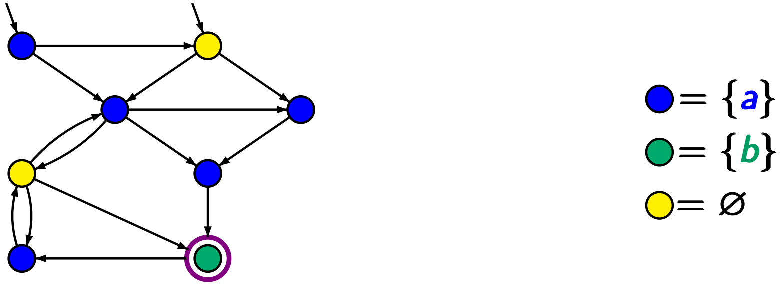
computation of $Sat(\exists(a \,\mathsf{U}\, b))$

add all states $s \in Sat(b)$ to T

as long as there are unprocessed states in T:

- choose such a state $s \in T$
- add all states $s' \in Pre(s) \cap Sat(a)$ to T

Example: until operator



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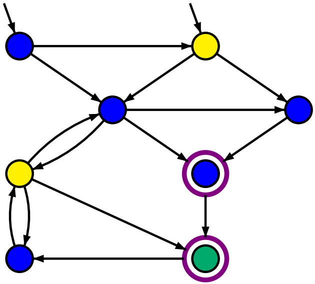

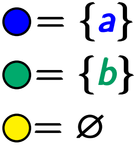

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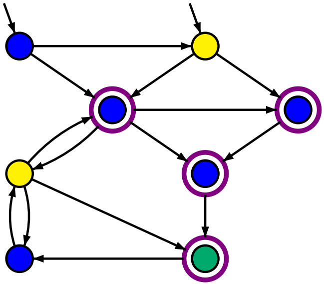

- blue state $= \{a\}$
- green state $= \{b\}$
- yellow state $= \varnothing$

computation of $Sat(\exists(a \, \mathsf{U} \, b))$

add all states $s \in Sat(b)$ to T

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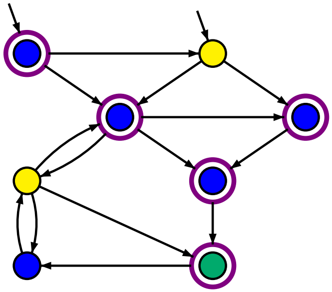

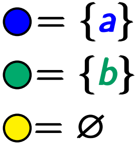

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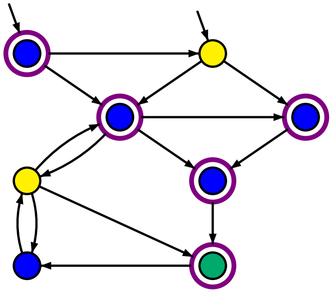
Example: until operator



● = $\{a\}$
● = $\{b\}$
● = $\varnothing$

computation of $Sat(\exists(a \,\mathsf{U}\, b)) = T$

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as long as there are unprocessed states in T:

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CTL model checking: treatment of ∃U

compute $\mathit{Sat}(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$ via an enumerative backward search

compute $Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$ via an enumerative backward search

$T := Sat(\Phi_2)$ ⟵ collects all states $s \models \exists(\Phi_1 \, \mathsf{U} \, \Phi_2)$

CTL model checking: treatment of $\exists U$

compute $Sat(\exists(\Phi_1 \, U \, \Phi_2))$ via an enumerative backward search

$T := Sat(\Phi_2)$ ⟵ collects all states $s \models \exists(\Phi_1 \, U \, \Phi_2)$

$E := Sat(\Phi_2)$ ⟵ set of states still to be expanded

CTL model checking: treatment of $\exists U$

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WHILE $E \neq \varnothing$ DO

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WHILE E ≠ ∅ DO
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```

compute $Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2))$ via an enumerative backward search

```
T := Sat(Φ2)  ⟵  collects all states s ⊨ ∃(Φ1 U Φ2)
E := Sat(Φ2)  ⟵  set of states still to be expanded
WHILE E ≠ ∅ DO
    select a state s′ ∈ E and remove s′ from E
    FOR ALL s ∈ Pre(s′) DO
        IF s ∈ Sat(Φ1) \ T THEN add s to T and E FI
    OD
OD
```

CTL model checking: treatment of ∃U

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OD
return T
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$T := Sat(\Phi_2)$ ⟵ collects all states $s \models \exists(\Phi_1 \, \mathsf{U} \, \Phi_2)$

$E := Sat(\Phi_2)$ ⟵ set of states still to be expanded

WHILE $E \neq \varnothing$ DO

  select a state $s' \in E$ and remove s' from E

  FOR ALL $s \in Pre(s')$ DO

    IF $s \in Sat(\Phi_1) \setminus T$ THEN add s to T and E FI

  OD

OD

return T

complexity: $\mathcal{O}(size(\mathcal{T}))$

CTL model checking: always operator

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expansion law: $\exists\Box\Phi \;\equiv\; \Phi \wedge \exists\bigcirc\exists\Box\Phi$

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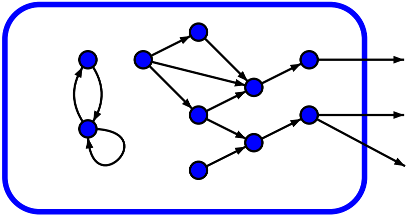
$Sat(\Phi)$



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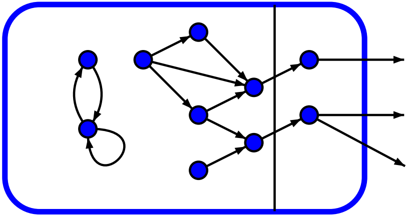

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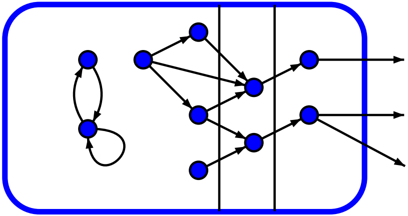

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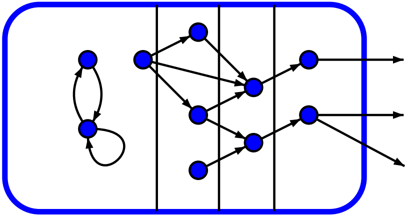

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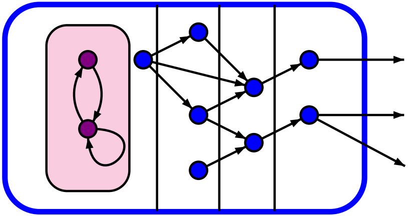

Computation of $Sat(\exists\Box\Phi)$

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WHILE E ≠ ∅ DO
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naïve implementation:
quadratic time complexity

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linear time implementation:

uses counters $c[s]$

Computation of $Sat(\exists\Box\Phi)$

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OD
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```

linear time implementation:

uses counters $c[s]$ for $|Post(s) \cap (T \cup E)|$

Computation of $Sat(\exists\Box\Phi)$ using counters

$T := Sat(\Phi)$; $E := S \setminus T$

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OD
```

Computation of $Sat(\exists\Box\Phi)$ using counters

$T := Sat(\Phi)$; $E := S \setminus T$

FOR ALL $s \in Sat(\Phi)$ DO $c[s] := |Post(s)|$ OD

use counters $c[s]$ for $|Post(s) \cap (T \cup E)|$

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WHILE E ≠ ∅ DO
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   FOR ALL s ∈ Pre(s') DO
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          remove s from T and add s to E
    FI
OD
```

```
T := Sat(Φ); E := S \ T
FOR ALL s ∈ Sat(Φ) DO  c[s] := |Post(s)| OD
```

> loop invariant: $c[s] = |Post(s) \cap (T \cup E)|$ for $s \in T$

```
WHILE  E ≠ ∅ DO
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   FOR ALL  s ∈ Pre(s′) DO
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    FI
OD
```

Computation of $Sat(\exists\Box\Phi)$ using counters

$T := Sat(\Phi)$; $E := S \setminus T$

FOR ALL $s \in Sat(\Phi)$ DO $c[s] := |Post(s)|$ OD

loop invariant: $c[s] = |Post(s) \cap (T \cup E)|$ for $s \in T$

WHILE $E \neq \varnothing$ DO

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IF $s \in T$ and ~~$Post(s) \cap (T \cup E) = \varnothing$~~ THEN

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  pick a state $s' \in E$ and remove s' from E

  FOR ALL $s \in Pre(s')$ DO

    IF $s \in T$ THEN

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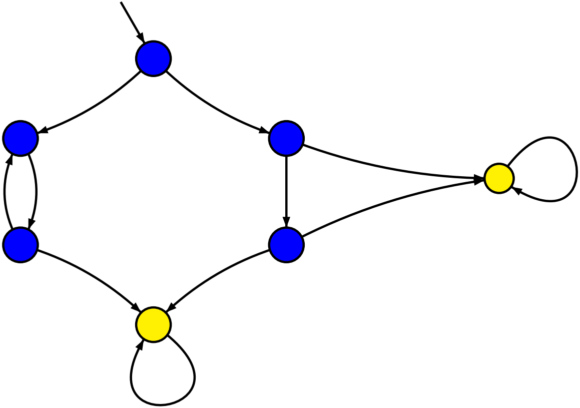
complexity: $\mathcal{O}(size(\mathcal{T}))$

Example: CTL model checking for $\exists\Box$

computation of $T = Sat(\exists\Box blue)$



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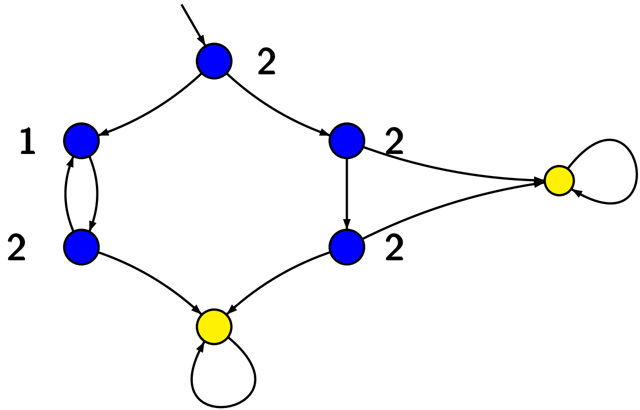

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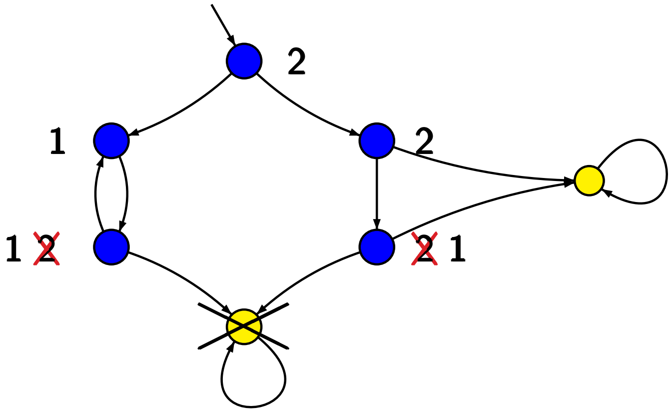

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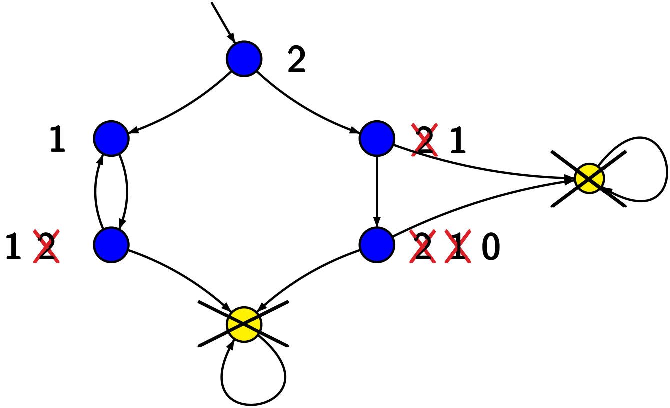

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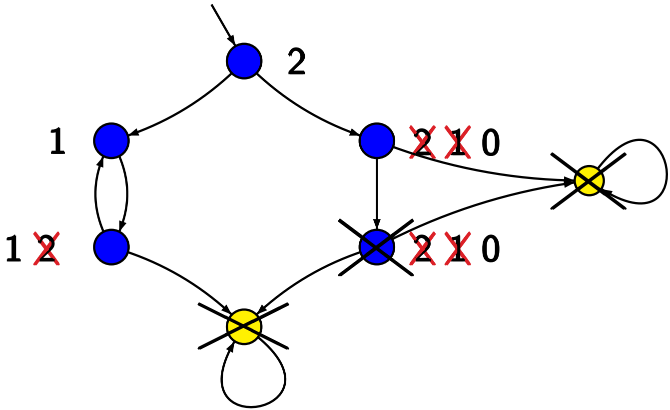
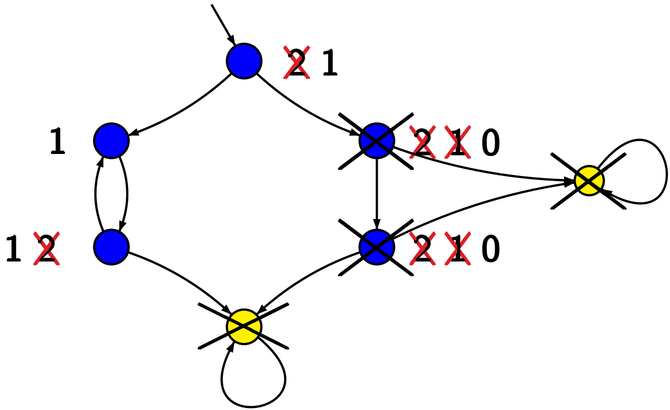


computation of $T = Sat(\exists\Box \mathit{blue})$



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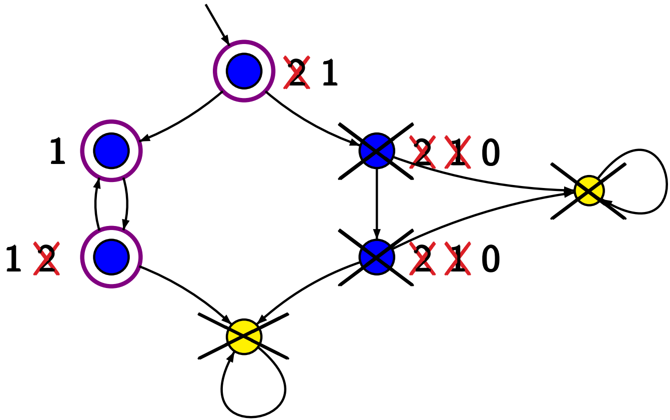

Recursive computation of satisfaction sets

case Φ is

$true$:	return S
$a \in AP$:	return $\{s \in S : a \in L(s)\}$
$\neg\Phi$:	return $S \setminus Sat(\Phi)$
$\Phi_1 \wedge \Phi_2$:	return $Sat(\Phi_1) \cap Sat(\Phi_2)$
$\exists\bigcirc\Phi$:	return $\{s \in S : Post(s) \cap Sat(\Phi) \neq \varnothing\}$
$\exists(\Phi_1 \mathsf{U} \Phi_2)$:	...
$\exists\Box\Phi$:	...

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$\exists(\Phi_1 \mathsf{U} \Phi_2)$:	... $\longleftarrow$ complexity $\mathcal{O}(size(\mathcal{T}))$
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time complexity: $\mathcal{O}(size(\mathcal{T}) \cdot |\Phi|)$

Recursive computation of $Sat(\ldots)$

$$Sat(\Phi_1 \wedge \Phi_2) = Sat(\Phi_1) \cap Sat(\Phi_2)$$

$$Sat(\neg\Phi) = S \setminus Sat(\Phi)$$

$$Sat(\exists\bigcirc\Phi) = \{s \in S : Post(s) \cap Sat(\Phi) = \varnothing\}$$

$$Sat(\exists(\Phi_1 \, \mathsf{U} \, \Phi_2)) = \bigcup_{n \geq 0} T_n \text{ where}$$

$$T_0 = Sat(\Phi_2)$$

$$T_{n+1} = \left\{s \in Sat(\Phi_1) : Post(s) \cap T_n \neq \varnothing\right\}$$

$$Sat(\exists\Box\Phi) = \bigcap_{n \geq 0} V_n \text{ where}$$

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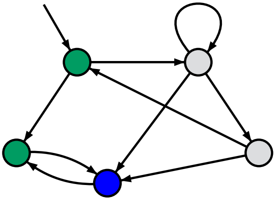

$$\Phi = \exists\Diamond\neg(\exists(a \, \mathsf{U} \, b) \vee \exists\Box\neg a)$$

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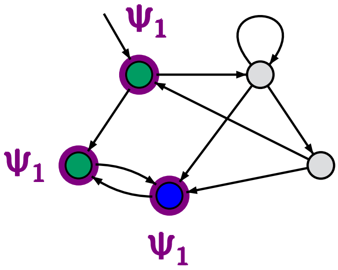
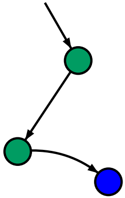


$$\Phi = \exists\Diamond\neg(\underbrace{\exists(a \,\mathsf{U}\, b)}_{\Psi_1} \vee \exists\Box\neg a)$$



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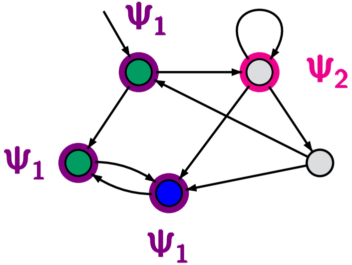

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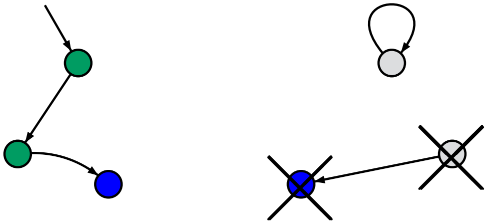

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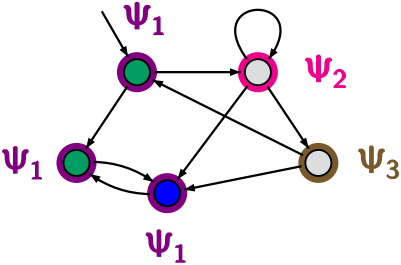

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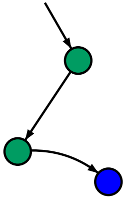

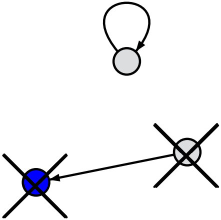

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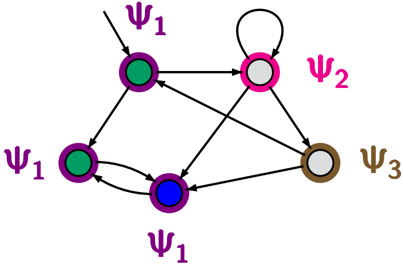

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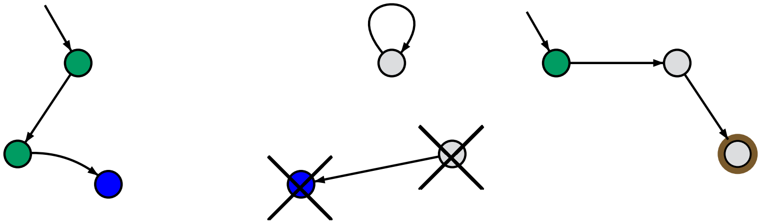

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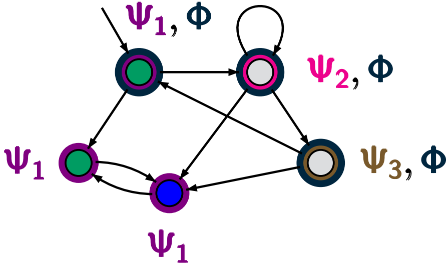

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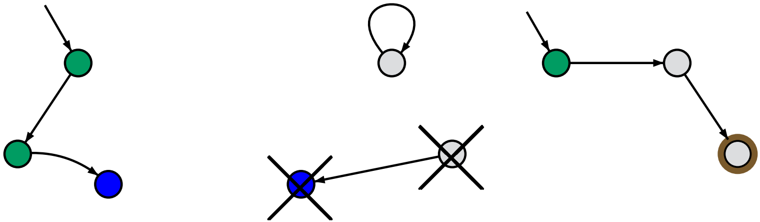

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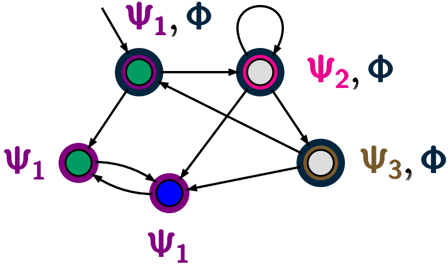

$$\mathcal{T} \models \Phi$$

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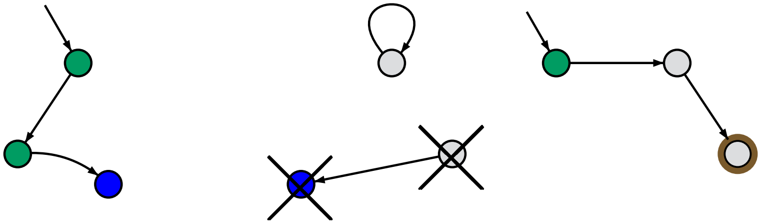

Complexity of CTL model checking

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Complexity of CTL/LTL model checking

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model complexity, i.e., for fixed specification:

CTL and **LTL**: $\mathcal{O}\big(\mathit{size}(\mathcal{T})\big)$

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model complexity, i.e., for fixed specification:

CTL and **LTL**: $\mathcal{O}\big(\mathit{size}(\mathcal{T})\big)$

If $\Phi \equiv \varphi$ then "often" we have: $|\Phi| = \exp(|\varphi|)$

CTL vs LTL

general observation:

CTL formulas are often "essentially longer" than equivalent **LTL** formulas, provided there is one.

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LTL-encoding the Hamilton path problem

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digraph G with n nodes	$\rightsquigarrow$	transition system $\mathcal{T}_G$ + LTL formula φ_n

s.t. G has a Hamilton path iff $\mathcal{T}_G \not\models \neg\varphi_n$

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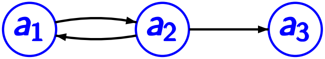

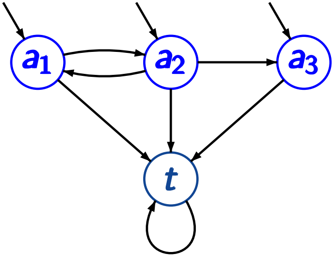

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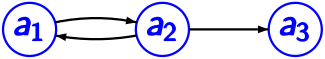

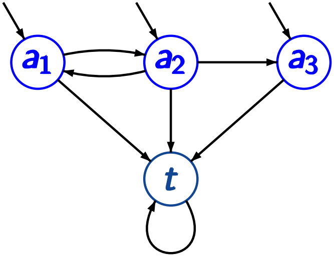

$AP = \{a_1, a_2, a_3\}$

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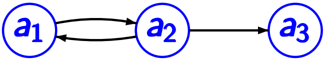

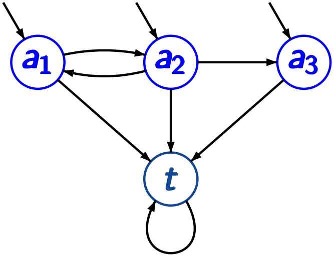

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CTL formula Φ_n, e.g., for $n = 3$:

$$
\begin{aligned}
&\big(a_1 \wedge \exists\bigcirc(a_2 \wedge \exists\bigcirc a_3)\big) \vee \big(a_1 \wedge \exists\bigcirc(a_3 \wedge \exists\bigcirc a_2)\big) \vee \\
&\big(a_2 \wedge \exists\bigcirc(a_1 \wedge \exists\bigcirc a_3)\big) \vee \big(a_2 \wedge \exists\bigcirc(a_3 \wedge \exists\bigcirc a_1)\big) \vee \\
&\big(a_3 \wedge \exists\bigcirc(a_1 \wedge \exists\bigcirc a_2)\big) \vee \big(a_3 \wedge \exists\bigcirc(a_2 \wedge \exists\bigcirc a_1)\big)
\end{aligned}
$$

Formulas φ'_n

LTL formula φ'_n such that $Words(\varphi'_n)$ is

$$\{\{a_{i_1}\} \ldots \{a_{i_n}\}\varnothing^\omega : (i_1, ..., i_n) \text{ permutation of } (1, ..., n)\}$$

Formulas φ'_n and Φ'_n

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$$\Psi(i_1, i_2, \ldots, i_n) \;=\; a_{i_1} \wedge \bigwedge_{k \neq i_1} \neg a_k \wedge \exists \bigcirc \Psi(i_2, \ldots, i_n)$$

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CTL vs LTL

CTL vs LTL

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