

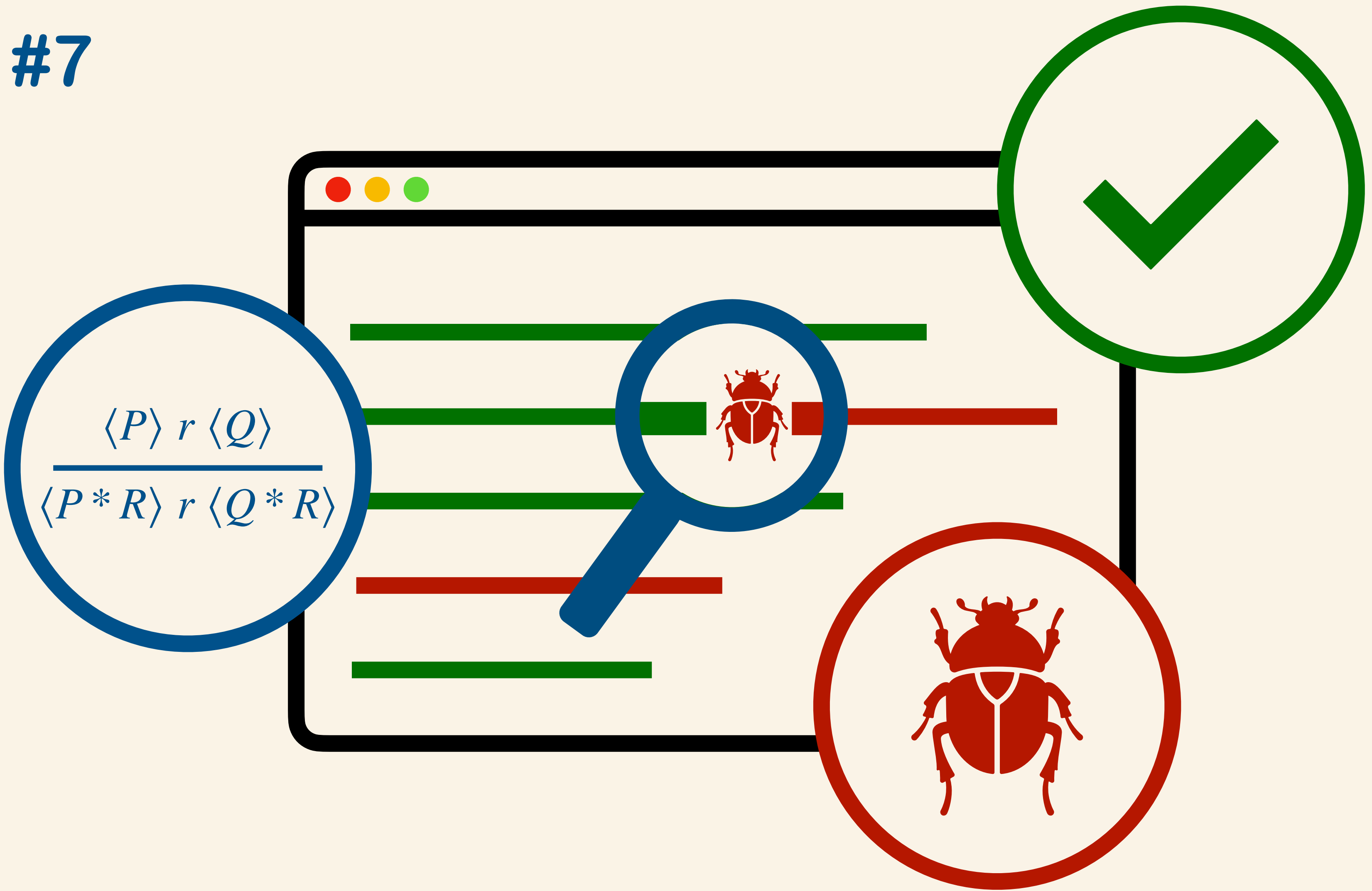


SCAN ME

Program Analysis

Lecture #7

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Footprint property

Footprint recipe

Given a command r

1. Derive the specification of r using **local axioms**
2. Apply rule frame to complete the specification

$$\begin{array}{l} \{P * x \mapsto _ \} \\ \{x \mapsto _ \} \\ [x] := 1; \\ \{x \mapsto 1 \} \\ a := [x] \\ \{x \mapsto 1 \wedge a = 1 \} \\ \{P * x \mapsto 1 \wedge a = 1 \} \end{array}$$

Footprint fails in SL

Counterexample:

We would like to derive

$$\{y \mapsto _ \} x := \text{alloc}(); \text{free}(x) \{y \mapsto _ \wedge y \neq x\}$$

$\{y \mapsto _ * \text{emp}\}$

$\{\text{emp}\}$

$x := \text{alloc}();$

$\{\exists v. v \mapsto _ \wedge x = v\}$

$\text{free}(x)$

$\{\exists v. x = v\}$

$\{\exists v. y \mapsto _ \wedge x = v\}$ // strongest derivable spec: **incomplete spec**

lossy: x held a location!

$\{x \mapsto _ \} \text{free}(x) \{\text{emp}\}$

Information loss

$\{x \mapsto _ \} [x] := y \{x \mapsto y \}$ // write

$\{y \mapsto v \} x := [y] \{x = v \wedge y \mapsto v \}$ // read

resources can grow

$\{\text{emp} \} x := \text{alloc}() \{x \mapsto _ \}$ // alloc

$\{x \mapsto _ \} \text{free}(x) \{\text{emp} \}$ // dispose

but should never shrink!

Incorrectness Separation Logic (ISL)

CAV 2020

Local Reasoning About the Presence of Bugs: Incorrectness Separation Logic



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Abstract. There has been a large body of work on local reasoning for proving the *absence* of bugs, but none for proving their *presence*. We present a new formal framework for local reasoning about the presence of bugs, building on two complementary foundations: 1) separation logic and 2) incorrectness logic. We explore the theory of this new *incorrectness separation logic* (ISL), and use it to derive a begin-anywhere, intra-procedural symbolic execution analysis that has no false positives *by construction*. In so doing, we take a step towards transferring modular, scalable techniques from the world of program verification to bug catching.

Keywords: Program logics · Separation logic · Bug catching

1 Introduction

There has been significant research on sound, local reasoning about the state for proving the absence of bugs (e.g., [2, 13, 26, 29, 30, 41]). Locality leads to techniques that are compositional *both* in code (concentrating on a program component) and in the resources accessed (spatial locality), without tracking the entire global state or the global program within which a component sits. Compositionality enables reasoning to scale to large teams and codebases: reasoning can be done even when a global program is not present (e.g., a library, or during program construction), without having to write the analogue of a test or verification harness, and the results of reasoning about components can be composed efficiently [11].

Meanwhile, many of the practical applications of symbolic reasoning have aimed at proving the *presence* of bugs (i.e., bug catching), rather than proving their absence (i.e., correctness). Logical bug catching methods include symbolic model checking [7, 12] and symbolic execution for testing [9]. These methods are usually formulated as global analyses; but, the rationale of local reasoning holds just as well for bug catching as it does for correctness: it has the potential to

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“bugs are a fundamental enough phenomenon to warrant a fundamental compositional theory for reasoning positively about their existence”



ISL = IL + SL

bug finding

IL

$[P] \text{ } r \text{ } [\epsilon : Q]$

local reasoning

SL

$\{P\} \text{ } r \text{ } \{Q\}$

$\frac{\{P\} \text{ } r \text{ } \{Q\}}{\{P * R\} \text{ } r \text{ } \{Q * R\}}$

ISL

$[P] \text{ } r \text{ } [\epsilon : Q]$

$\frac{[P] \text{ } r \text{ } [\epsilon : Q]}{[P * R] \text{ } r \text{ } [\epsilon : Q * R]}$

Regular commands

regular
command

$r ::=$

e

atomic
command

choice

Kleene
star

$r_1; r_2$

$r_1 + r_2$

$r^\star$

$e ::=$ skip

$b?$

$x := a$

$x := [y]$

simplified

// read

$[x] := y$

// write

$x := \text{alloc}()$

$\text{free}(x)$

can fail

$\text{error}()$

...

Disclaimer

for the sake of presentation, some
technical aspects are not fully detailed



Local axioms: write

$$\text{SL} \quad \frac{}{\{x \mapsto _ \} [x] := y \{x \mapsto y \}}$$

$$[x \mapsto v] [x] := y \text{ [ok : } x \mapsto y \text{]}$$

must put a
value

$$[x = \text{nil}] [x] := y \text{ [er : } x = \text{nil} \text{]}$$

null pointer
dereference

Local axioms: read

SL

$$\frac{}{\{y \mapsto v\} x := [y] \{x = v \wedge y \mapsto v\}}$$

$$[y \mapsto v] x := [y] [\text{ok} : x = v \wedge y \mapsto v]$$

$$[y = \text{nil}] x := [y] [\text{er} : y = \text{nil}]$$

null pointer
dereference

Local axioms: allocation

SL

$$\frac{}{\{\text{emp}\} \ x := \text{alloc}() \ \{x \mapsto _ \}}$$

$$[x \dot{=} x'] \ x := \text{alloc}() \ [\text{ok} : x \mapsto _]$$

needed for
footprint

Local axioms: dispose (1st try)

SL

$$\frac{}{\{x \mapsto _ \} \text{ free}(x) \{ \text{emp} \}}$$

$$[x \mapsto v] \text{ free}(x) [\text{ok} : \text{emp}]$$

must put a
value

$$[x = \text{nil}] \text{ free}(x) [\text{er} : x = \text{nil}]$$

null pointer
dereference

Unsound Frame rule

$$\frac{[P] \text{ } r \text{ } [\epsilon : Q]}{[P * R] \text{ } r \text{ } [\epsilon : Q * R]}$$

$$\frac{\frac{\frac{}{[x \mapsto v] \text{ free}(x) [\text{ok} : \text{emp}]} \text{ [free]}}{[x \mapsto v * x \mapsto v] \text{ free}(x) [\text{ok} : \text{emp} * x \mapsto v]} \text{ [frame]}}{[\text{false}] \text{ free}(x) [\text{ok} : x \mapsto v]} \text{ [cons]}$$

the only sound
under approximation
can be false

this can be fixed by using a
monotonic heap model
(and we will recover
completeness)

Solution

assertion

$P ::=$ true | false | $a_1 < a_2$ | $a_1 = a_2$ | ...
| $\neg P$ | $P_1 \wedge P_2$ | $\exists x. P$ | ...
| emp
| $a_1 \mapsto a_2$
| $P_1 * P_2$
| $x \nrightarrow$

Boolean and
classical
assertions

structural
assertions

track deallocated
locations

Satisfaction: structural

$\langle s, h \rangle \models a_1 \mapsto a_2$ iff $\text{dom}(h) = \{ \llbracket a_1 \rrbracket s \}$ and $h(\llbracket a_1 \rrbracket s) = \llbracket a_2 \rrbracket s$

$\langle s, h \rangle \models \text{emp}$ iff h is the empty map $[\]$

$\langle s, h \rangle \models P_1 * P_2$ iff $\exists h_1, h_2 . \langle s, h_1 \rangle \models P_1$ and $\langle s, h_2 \rangle \models P_2$ and $h = h_1 \bullet h_2$

$\langle s, h \rangle \models x \nrightarrow$ iff $\text{dom}(h) = \{ s(x) \}$ and $h(s(x)) = \perp$

Notably: $x \mapsto v * x \nrightarrow \equiv \text{false} \equiv x \nrightarrow * x \nrightarrow$

$y \mapsto v * x \nrightarrow \equiv y \mapsto v * x \nrightarrow \wedge x \neq y$

Local axioms: dispose

SL

$$\frac{}{\{x \mapsto _ \} \text{free}(x) \{ \text{emp} \}}$$

$$[x \mapsto v] \text{free}(x) [\text{ok} : x \not\mapsto _]$$

must put a
value

track deallocated
locations

this way resources
cannot shrink

$$[x = \text{nil}] \text{free}(x) [\text{er} : x = \text{nil}]$$

null pointer
dereference

Example

$$\frac{\frac{\frac{}{[x \mapsto v] \text{ free}(x) \text{ [ok : } x \not\mapsto \text{]}} \text{ [free]}}{[x \mapsto v * x \mapsto v] \text{ free}(x) \text{ [ok : } x \not\mapsto * x \mapsto v \text{]}} \text{ [frame]}}{[false] \text{ free}(x) \text{ [ok : false]}} \text{ [cons]}$$

sound
under approximation!

Footprint holds in ISL

We would like to derive

$$[y \mapsto _] \ x := \text{alloc}() ; \text{free}(x) \ [\text{ok} : y \mapsto _ \wedge x \not\mapsto _ \wedge y \neq x]$$

$$[y \mapsto _ * \text{emp}]$$

$$[\text{emp}]$$

$$x := \text{alloc}();$$

$$[x \mapsto v]$$

$$\text{free}(x)$$

$$[x \not\mapsto _]$$

$$[\text{ok} : y \mapsto _ * x \not\mapsto _ \wedge y \neq x]$$

Additional local axioms

$$[x \not\mapsto] [x] := y [er : x \not\mapsto]$$

use after free
errors

$$[y \not\mapsto] x := [y] [er : y \not\mapsto]$$

$$[x \not\mapsto] \text{free}(x) [er : x \not\mapsto]$$

double free
error

$$[y \not\mapsto] x := \text{alloc}() [ok : x \mapsto v \wedge x = y]$$

reuse of
deallocated
locations

Soundness and completeness

Relational semantics

$$\llbracket \text{skip} \rrbracket_{\text{ok}} \triangleq \{(\sigma, \sigma)\}$$

$$\llbracket b? \rrbracket_{\text{ok}} \triangleq \{(\sigma, \sigma) \mid \sigma = \langle s, h \rangle \wedge s \models b\}$$

$$\llbracket x := a \rrbracket_{\text{ok}} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto \llbracket a \rrbracket s], h)\}$$

$$\llbracket \text{error}() \rrbracket_{\text{ok}} \triangleq \emptyset$$

$$\llbracket \text{skip} \rrbracket_{\text{er}} \triangleq \emptyset$$

$$\llbracket b? \rrbracket_{\text{er}} \triangleq \emptyset$$

$$\llbracket x := a \rrbracket_{\text{er}} \triangleq \emptyset$$

$$\llbracket \text{error}() \rrbracket_{\text{er}} \triangleq \{(\sigma, \sigma)\}$$

$$\llbracket x := [y] \rrbracket_{\text{ok}} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto v], h \rangle) \mid v = h(s(y)) \in \mathbb{Z}\}$$

$$\llbracket x := [y] \rrbracket_{\text{er}} \triangleq \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(y) = \text{nil} \vee h(s(y)) = \perp\}$$

$$\llbracket [x] := y \rrbracket_{\text{ok}} \triangleq \{(\langle s, h \rangle, \langle s, h[s(x) \mapsto s(y)] \rangle) \mid h(s(x)) \in \mathbb{Z}\}$$

$$\llbracket [x] := y \rrbracket_{\text{er}} \triangleq \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(x) = \text{nil} \vee h(s(x)) = \perp\}$$

$$\llbracket x := \text{alloc}() \rrbracket_{\text{ok}} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto n], h[n \mapsto v] \rangle) \mid v \in \mathbb{Z} \wedge (n \notin \text{dom}(h) \vee h(n) = \perp)\}$$

$$\llbracket x := \text{alloc}() \rrbracket_{\text{er}} \triangleq \emptyset$$

$$\llbracket \text{free}(x) \rrbracket_{\text{ok}} \triangleq \{(\langle s, h \bullet [s(x) \mapsto v] \rangle, \langle s, h \bullet [s(x) \mapsto \perp] \rangle) \mid s(x) \in \mathbb{N} \wedge v \in \mathbb{Z}\}$$

$$\llbracket \text{free}(x) \rrbracket_{\text{er}} \triangleq \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(x) = \text{nil} \vee h(s(x)) = \perp\}$$

Actual ISL rules

SKIP $\vdash [\mathbf{emp}] \text{ skip } [ok : \mathbf{emp}]$	ASSIGN $\vdash [x=x'] x := e [ok : x=e[x'/x]]$	HAVOC $\vdash [x=x'] x := * [ok : x=v]$		
ASSUME $\vdash [\mathbf{emp}] \text{ assume}(B) [ok : B]$	ERROR $\vdash [\mathbf{emp}] \text{ L: error } [er(L) : \mathbf{emp}]$	FRAME $\frac{\vdash [p] \mathbb{C} [\epsilon : q] \quad \text{mod}(\mathbb{C}) \cap \text{fv}(r) = \emptyset}{\vdash [p * r] \mathbb{C} [\epsilon : q * r]}$	ALLOC1 $\vdash [x=x'] x := \text{alloc}() [ok : x \mapsto -]$	
SEQ1 $\frac{\vdash [p] \mathbb{C}_1 [er(L) : q]}{\vdash [p] \mathbb{C}_1; \mathbb{C}_2 [er(L) : q]}$	SEQ2 $\frac{\vdash [p] \mathbb{C}_1 [ok : r] \quad \vdash [r] \mathbb{C}_2 [\epsilon : q]}{\vdash [p] \mathbb{C}_1; \mathbb{C}_2 [\epsilon : q]}$	LOOP1 $\vdash [p] \mathbb{C}^* [ok : p]$	FREE $\vdash [x \mapsto e] \text{ L: free}(x) [ok : x \not\mapsto]$	ALLOC2 $\vdash [x=x' * y \not\mapsto] x := \text{alloc}() [ok : x=y * y \mapsto -]$
CHOICE $\frac{\vdash [p] \mathbb{C}_i [\epsilon : q] \quad \text{for some } i \in \{1, 2\}}{\vdash [p] \mathbb{C}_1 + \mathbb{C}_2 [\epsilon : q]}$	EXIST $\frac{\vdash [p] \mathbb{C} [\epsilon : q] \quad x \notin \text{fv}(\mathbb{C})}{\vdash [\exists x. p] \mathbb{C} [\epsilon : \exists x. q]}$	LOOP2 $\frac{\vdash [p] \mathbb{C}^*; \mathbb{C} [\epsilon : q]}{\vdash [p] \mathbb{C}^* [\epsilon : q]}$	FREEER $\vdash [x \not\mapsto] \text{ L: free}(x) [er(L) : x \not\mapsto]$	REENULL $\vdash [x=\mathbf{null}] \text{ L: free}(x) [er(L) : x=\mathbf{null}]$
CONS $\frac{p' \Rightarrow p \quad \vdash [p'] \mathbb{C} [\epsilon : q'] \quad q \Rightarrow q'}{\vdash [p] \mathbb{C} [\epsilon : q]}$	DISJ $\frac{\vdash [p_1] \mathbb{C} [\epsilon : q_1] \quad \vdash [p_2] \mathbb{C} [\epsilon : q_2]}{\vdash [p_1 \vee p_2] \mathbb{C} [\epsilon : q_1 \vee q_2]}$	LOAD $\vdash [x=x' * y \mapsto e] \text{ L: } x := [y] [ok : x=e[x'/x] * y \mapsto e[x'/x]]$	STORE $\vdash [x \mapsto e] \text{ L: } [x] := y [ok : x \mapsto y]$	
		LOADER $\vdash [y \not\mapsto] \text{ L: } x := [y] [er(L) : y \not\mapsto]$	STOREER $\vdash [x \not\mapsto] \text{ L: } [x] := y [er(L) : x \not\mapsto]$	
		LOADNULL $\vdash [y=\mathbf{null}] \text{ L: } x := [y] [er(L) : y=\mathbf{null}]$	STORENULL $\vdash [x=\mathbf{null}] \text{ L: } [x] := y [er(L) : x=\mathbf{null}]$	
SUBST $\frac{\vdash [p] \mathbb{C} [\epsilon : q] \quad y \notin \text{fv}(p, \mathbb{C}, q)}{\vdash [p[y/x]] \mathbb{C}[y/x] [\epsilon : q[y/x]]}$	LOCAL $\frac{\vdash [p] \mathbb{C} [\epsilon : q]}{\vdash [\exists x. p] \text{ local } x \text{ in } \mathbb{C} [\epsilon : \exists x. q]}$			

Correctness

Th. [*correctness*]

If $[P] \ r \ [\epsilon : Q]$ then $Q \subseteq \llbracket r \rrbracket \epsilon P$

Proof. By induction on the derivation.

Footprint theorem

Th. [*footprint*]

Any valid ISL triple $[\sigma_P] \ r \ [\epsilon : \sigma_Q]$ can be derived

Proof. See CAV2020 paper for details.

Final considerations on SL

ISL = IL + SL
for bug
catching!

ISL address compositional bug catching

targets memory safety bugs (use-after-free)

no-false-positives theorem: all bugs are true

Questions

Question 1

Is the axiom $[x \mapsto _][x] := y \text{ [ok : } x \mapsto y]$ sound?

$$\frac{(x \mapsto v) \Rightarrow (x \mapsto _) \quad [x \mapsto v][x] := y \text{ [ok : } x \mapsto y]}{[x \mapsto _][x] := y \text{ [ok : } x \mapsto y]}$$

Question 2

Prove that rule [*conj] is **unsound**

$$\frac{[P_1] \text{ } r \text{ } [Q_1] \quad [P_2] \text{ } r \text{ } [Q_2]}{[P_1 * P_2] \text{ } r \text{ } [Q_1 * Q_2]} \text{[*conj]}$$

Consider $[x = 0] \text{ } x := 1 \text{ } [x = 1]$ and $[x = 1] \text{ } x := 1 \text{ } [x = 1]$

By rule [*conj] we could derive $[false] \text{ } x := 1 \text{ } [x = 1]$

which is not sound!