

Unreachable statements

JLS §14.20: Conservative flow analysis at compile-time.

Static predicates:

reachable(α) \iff the phrase at position α is reachable

normal(α) \iff the phrase at position α can complete normally

Fact: *normal*(α) implies *reachable*(α).

Conditional compilation:

$\text{while (false)}^\alpha \text{stm} \implies \text{reachable}(\alpha) = \text{False}$

$\text{if (false)}^\alpha \text{stm} \implies \text{reachable}(\alpha) = \text{True}$

Constraints for method bodies:

reachable(*firstPos*) = *True*

normal(*firstPos*) = *False*

Reachability constraints

$\alpha;$	$\mathit{normal}(\alpha) \Leftrightarrow \mathit{reachable}(\alpha)$
$\alpha(\beta \text{ exp};)$	$\mathit{normal}(\alpha) \Leftrightarrow \mathit{reachable}(\alpha)$
$\alpha\{\beta_1 \text{ stm}_1 \dots \beta_n \text{ stm}_n\}$	$\mathit{reachable}(\beta_1) \Leftrightarrow \mathit{reachable}(\alpha),$ $\mathit{reachable}(\beta_{i+1}) \Leftrightarrow \mathit{normal}(\beta_i),$ $\mathit{normal}(\alpha) \Leftrightarrow \mathit{normal}(\beta_n)$
$\alpha \text{ if } (\beta \text{ exp}) \gamma \text{ stm}_1$ $\text{ else } \delta \text{ stm}_2$	$\mathit{reachable}(\gamma) \Leftrightarrow \mathit{reachable}(\alpha),$ $\mathit{reachable}(\delta) \Leftrightarrow \mathit{reachable}(\alpha),$ $\mathit{normal}(\alpha) \Leftrightarrow \mathit{normal}(\gamma) \vee \mathit{normal}(\delta)$
$\alpha \text{ while } (\beta \text{ exp}) \gamma \text{ stm}$	$\mathit{reachable}(\gamma) \Leftrightarrow \mathit{reachable}(\alpha)$ and $\beta \text{ exp}$ is not a constant expression with value <i>False</i> , $\mathit{normal}(\alpha) \Leftrightarrow \mathit{reachable}(\alpha)$ and $\beta \text{ exp}$ is not a constant expression with value <i>True</i>

Reachability constraints (continued)

$\alpha lab: \beta stm$	$reachable(\beta) \Leftrightarrow reachable(\alpha)$, $normal(\alpha) \Leftrightarrow normal(\beta)$ or there exists a reachable statement break lab inside βstm that can exit βstm
$\alpha break lab;$	$\neg normal(\alpha)$
$\alpha continue lab;$	$\neg normal(\alpha)$
$\alpha return;$	$\neg normal(\alpha)$
$\alpha return \beta exp;$	$\neg normal(\alpha)$
$\alpha throw \beta exp;$	$\neg normal(\alpha)$

Reachability constraints (continued)

α try β block_t
 catch $(E_1 x_1) \gamma^1$ block₁
 ⋮
 catch $(E_n x_n) \gamma^n$ block_n

$reachable(\beta) \Leftrightarrow reachable(\alpha)$,
 $reachable(\gamma_i) \Leftrightarrow reachable(\alpha)$ and
 $E_i \not\leq_h E_j$ for $1 \leq j < i$ and block_t can
 throw an exception F with $F \leq_h E_i$ or
 $E_i \leq_h F$,
 $normal(\alpha) \Leftrightarrow normal(\beta) \vee$
 $\bigvee_{1 \leq i \leq n} normal(\gamma_i)$

α (β stm finally γ block)

$reachable(\beta) \Leftrightarrow reachable(\alpha)$,
 $reachable(\gamma) \Leftrightarrow reachable(\alpha)$,
 $normal(\alpha) \Leftrightarrow normal(\beta) \wedge normal(\gamma)$

α synchronized (β exp)
 γ stm

$reachable(\gamma) \Leftrightarrow reachable(\alpha)$,
 $normal(\alpha) \Leftrightarrow normal(\gamma)$

“can exit” and “can throw”

Definition. An abrupton at position α **can exit** stm , if for every substatement $\beta(\gamma_s \text{ finally } \delta b)$ of stm such that α is in s the predicate $normal(\delta)$ is true.

Definition. A statement stm **can throw** an exception E , if one of the following conditions is true:

- $E = RuntimeException$ or $E = Error$
- stm contains a **reachable** statement $\alpha \text{ throw } \beta \text{ exp}$ such that $\mathcal{T}(\beta) = E$, the exception E is not caught in stm and an abrupton at position α can exit stm
- stm contains a **reachable** method invocation $\alpha c/m(\text{exprs})$ such that E occurs in the throws clause of m in c , the exception E is not caught in stm and an abrupton at position α can exit stm .

The rules of definite assignment (JLS §16)

$x \in \textit{before}(\alpha)$

The variable x is definitely assigned **before** the evaluation of the statement or expression at position α .

$x \in \textit{after}(\alpha)$

The variable x is definitely assigned **after** the statement or expression at position α when this statement or expression completes **normally**.

$x \in \textit{true}(\alpha)$

The variable x is definitely assigned **after** the evaluation of the expression at position α when this expression evaluates to **true**.

$x \in \textit{false}(\alpha)$

The variable x is definitely assigned **after** the evaluation of the expression at position α when this expression evaluates to **false**.

$x \in \textit{vars}(\alpha)$

The position α is in the **scope** of the local variable, formal parameter or catch parameter x .

Definite assignment for boolean expressions

α true	$true(\alpha) = before(\alpha), false(\alpha) = vars(\alpha)$
α false	$true(\alpha) = vars(\alpha), false(\alpha) = before(\alpha)$
$\alpha(!\beta e)$	$before(\beta) = before(\alpha),$ $true(\alpha) = false(\beta), false(\alpha) = true(\beta)$
$\alpha(\beta e_0 ? \gamma e_1 : \delta e_2)$	$before(\beta) = before(\alpha),$ $before(\gamma) = true(\beta), before(\delta) = false(\beta),$ $true(\alpha) = true(\gamma) \cap true(\delta),$ $false(\alpha) = false(\gamma) \cap false(\delta)$

Constraint: $\mathcal{T}(\alpha) = \text{boolean}$

Constraint: $after(\alpha) = true(\alpha) \cap false(\alpha)$

Definite assignment for boolean expressions (continued)

$$\alpha(\beta e_1 \ \&\& \ \gamma e_2) \quad \left| \quad \begin{array}{l} \textit{before}(\beta) = \textit{before}(\alpha), \textit{before}(\gamma) = \textit{true}(\beta), \\ \textit{true}(\alpha) = \textit{true}(\gamma), \textit{false}(\alpha) = \textit{false}(\beta) \cap \textit{false}(\gamma) \end{array} \right.$$

$$\alpha(\beta e_1 \ || \ \gamma e_2) \quad \left| \quad \begin{array}{l} \textit{before}(\beta) = \textit{before}(\alpha), \textit{before}(\gamma) = \textit{false}(\beta), \\ \textit{true}(\alpha) = \textit{true}(\beta) \cap \textit{true}(\gamma), \textit{false}(\alpha) = \textit{false}(\gamma) \end{array} \right.$$

Constraint: If $\mathcal{T}(\alpha) = \text{boolean}$ and ${}^\alpha \textit{exp}$ is of a different kind, then $\textit{true}(\alpha) = \textit{after}(\alpha)$ and $\textit{false}(\alpha) = \textit{after}(\alpha)$.

Definite assignment for arbitrary expressions

${}^{\alpha}loc$	$after(\alpha) = before(\alpha), loc \in before(\alpha)$
${}^{\alpha}lit$	$after(\alpha) = before(\alpha)$
${}^{\alpha}(loc = {}^{\beta}e)$	$before(\beta) = before(\alpha), loc \in vars(\alpha),$ $after(\alpha) = after(\beta) \cup \{loc\}$
${}^{\alpha}({}^{\beta}e_0 ? {}^{\gamma}e_1 : {}^{\delta}e_2)$	$before(\beta) = before(\alpha), before(\gamma) = true(\beta),$ $before(\delta) = false(\beta),$ $after(\alpha) = after(\gamma) \cap after(\delta)$
${}^{\alpha}c.f$	$after(\alpha) = before(\alpha)$

Definite assignment for arbitrary expressions

Constraints for an expression $\alpha \text{ exp}$ with direct subexpressions $\beta_1 \text{ exp}_1, \dots, \beta_n \text{ exp}_n$:

- $\text{before}(\beta_1) = \text{before}(\alpha)$,
- $\text{before}(\beta_{i+1}) = \text{after}(\beta_i)$ for $i = 1, \dots, n - 1$,
- $\text{after}(\alpha) = \text{after}(\beta_n)$.

The direct subexpressions of an expression

Expression at position α	Direct subexpressions of α
$\alpha(uop \beta \text{ exp})$	$\beta \text{ exp}$
$\alpha(\beta \text{ exp}_1 \text{ bop } \gamma \text{ exp}_2)$	$\beta \text{ exp}_1, \gamma \text{ exp}_2$
$\alpha(c.f = \beta \text{ exp})$	$\beta \text{ exp}$
$\alpha(\beta_1 \text{ exp}_1, \dots, \beta_n \text{ exp}_n)$	$\beta_1 \text{ exp}_1, \dots, \beta_n \text{ exp}_n$
$\alpha(c.m^\beta(\text{exps}))$	$\beta(\text{exps})$

The direct subexpressions of an expression

Expression at position α	Direct subexpressions of α
$\alpha(\beta \text{ exp instance of } c)$	$\beta \text{ exp}$
$\alpha((c) \beta \text{ exp})$	$\beta \text{ exp}$
$\alpha(\beta \text{ exp}.c/f)$	$\beta \text{ exp}$
$\alpha(\beta \text{ exp}_1.c/f = \gamma \text{ exp}_2)$	$\beta \text{ exp}_1, \gamma \text{ exp}_2$
$\alpha(\beta \text{ exp}.c/m \gamma(\text{exps}))$	$\beta \text{ exp}, \gamma(\text{exps})$
$\alpha \text{new } c.c/m \beta(\text{exps})$	$\beta(\text{exps})$
$\alpha(\beta \text{ exp}_1[\gamma \text{ exp}_2])$	$\beta \text{ exp}_1, \gamma \text{ exp}_2$
$\alpha(\beta \text{ exp}_1[\gamma \text{ exp}_2] = \delta \text{ exp}_3)$	$\beta \text{ exp}_1, \gamma \text{ exp}_2, \delta \text{ exp}_3$
$\alpha(\text{new } A[\beta^1 \text{ exp}_1] \dots [\beta^n \text{ exp}_n][\] \dots [\])$	$\beta^1 \text{ exp}_1, \dots, \beta^n \text{ exp}_n$

Definite assignment for statements

$\alpha;$	$after(\alpha) = before(\alpha)$
$\alpha(\beta \text{ exp};)$	$before(\beta) = before(\alpha), after(\alpha) = after(\beta)$
$\alpha\{\beta_1 \text{ stm}_1 \dots \beta_n \text{ stm}_n\}$	$before(\beta_1) = before(\alpha),$ $before(\beta_{i+1}) = after(\beta_i) \text{ for } i = 1, \dots, n-1,$ $after(\alpha) = after(\beta_n) \cap vars(\alpha)$
$\alpha \text{ if } (\beta \text{ exp}) \gamma \text{ stm}_1$ $\text{ else } \delta \text{ stm}_2$	$before(\beta) = before(\alpha),$ $before(\gamma) = true(\beta), before(\delta) = false(\beta),$ $after(\alpha) = after(\gamma) \cap after(\delta)$
$\alpha \text{ while } (\beta \text{ exp}) \gamma \text{ stm}$	$before(\beta) = before(\alpha), before(\gamma) = true(\beta),$ $after(\alpha) = false(\beta)$

Definite assignment for statements (continued)

$\alpha lab: \beta stm$	$before(\beta) = before(\alpha),$ $after(\alpha) = after(\beta) \cap break(\beta, lab)$
$\alpha break lab;$	$after(\alpha) = vars(\alpha)$
$\alpha continue lab;$	$after(\alpha) = vars(\alpha)$
$\alpha return;$	$after(\alpha) = vars(\alpha)$
$\alpha return \beta exp;$	$before(\beta) = before(\alpha), after(\alpha) = vars(\alpha)$
$\alpha throw \beta exp;$	$before(\beta) = before(\alpha), after(\alpha) = vars(\alpha)$

Definition: $x \in break(\alpha, lab) :\iff$

- x is in $before(\beta)$ for each statement $\beta break lab$ inside the statement at position α that can exit α and
- x is in $after(\beta)$ for each statement $\beta(s \text{ finally } b)$ inside α such that s contains a $break lab$ that can exit α .

Definite assignment for statements (continued)

α try β block _t catch $(E_1 x_1) \gamma_1$ block ₁ ⋮ catch $(E_n x_n) \gamma_n$ block _n	$before(\beta) = before(\alpha),$ $before(\gamma_i) = before(\alpha) \cup \{x_i\},$ $after(\alpha) = after(\beta) \cap \bigcap_{1 \leq i \leq n} after(\gamma_i)$
$\alpha(\beta$ stm finally γ block)	$before(\beta) = before(\alpha),$ $before(\gamma) = before(\alpha),$ $after(\alpha) = \{x \in after(\beta) \mid$ there is no $x = exp$ in γ block $\} \cup after(\gamma)$
α synchronized $(\beta$ exp) γ stm	$before(\beta) = before(\alpha),$ $before(\gamma) = after(\beta),$ $after(\alpha) = after(\gamma)$

Run-time compatible

Definition. $A \sqsubseteq B : \iff$ one of the following conditions is true:

- A and B are primitive types and $A = B$
- A and B are reference types and $A \preceq B$

Lemma:

- $A \sqsubseteq A$.
- If $A \sqsubseteq B$ and $B \sqsubseteq C$, then $A \sqsubseteq C$.
- If $A \sqsubseteq B$ and $B \sqsubseteq A$, then $A = B$.
- $A[] \sqsubseteq B[] \iff A \sqsubseteq B$.

Definition. f is a **frame in state** n of thread q , iff one of the following conditions is true:

- $f = (\text{meth}_n^q, \text{restbody}_n^q, \text{pos}_n^q, \text{locals}_n^q)$
- f is an element of frames_n^q

Reference is used in a state

Definition. A reference ref is **used** in state n , iff one of the following conditions is true:

- there exists a field c/f such that $globals_n(c/f) = ref$
- there exists an r and a field c/f such that $getField_n(r, c/f) = ref$
- there exists an r and an $i \in \mathbb{N}$ such that $getElement_n(r, i) = ref$
- there exists a frame $(_, restbody^*, _, locals^*)$ in state n of a thread q and one of the following conditions is true:
 - there exists a variable loc such that $locals^*(loc) = ref$
 - there exists a position α such that $restbody^*/\alpha = ref$
 - there exists a position α such that $restbody^*/\alpha = Return(ref)$
 - there exists a position α such that $restbody^*/\alpha = Exc(ref)$

Theorem: Java is type safe

Theorem. Assume that $(meth^*, restbody^*, pos^*, locals^*)$ is a frame in state n of thread q . Then the following invariants are satisfied:

(def1) *before* $(pos^*) \subseteq dom(locals^*)$.

(def2) If $restbody^*/pos^*$ is normal, then *after* $(pos^*) \subseteq dom(locals^*)$.

(def3) If $restbody^*/pos^* = True$, then *true* $(pos^*) \subseteq dom(locals^*)$.

(def4) If $restbody^*/pos^* = False$, then *false* $(pos^*) \subseteq dom(locals^*)$.

(def5) If $restbody^*/pos^* = Break(l)$, then
break $(pos^*, l) \subseteq dom(locals^*)$.

(def6) If the frame is not the current frame of q and $body(meth^*)/pos^*$ is a method invocation then *after* $(pos^*) \subseteq dom(locals^*)$.

(reach) *reachable* (pos^*) .

Theorem: Java is type safe (continued)

- (norm)** If $restbody^* / \alpha = Norm$, then $normal(\alpha)$.
- (val)** If $restbody^* / \alpha$ is a value of type B , then $B \sqsubseteq \mathcal{T}(\alpha)$, where $\mathcal{T}(\alpha)$ is the compile-time type of position α in $body(meth^*)$.
- (undef)** The constant $undef$ does not occur in $restbody^*$.
- (loc1)** If $x \in dom(locals^*)$, then $locals^*(x) \in Val$.
- (loc2)** If pos^* is in the scope of a **local variable** declaration of a variable x of type A and $x \in dom(locals^*)$, then $locals^*(x)$ is a value of type $B \sqsubseteq A$.
- (loc3)** If pos^* is in the scope of a **formal parameter** x of type A , then $locals^*(x)$ is a value of type $B \sqsubseteq A$.
- (loc4)** If pos^* is in the scope of a **catch parameter** x of type E , then $locals^*(x)$ is a value of type $F \preceq_h E$.
- (loc5)** If pos^* is in class A and pos^* is in the body of an instance method or in the body of a constructor, then $locals^*(this)$ is a value of type $B \preceq_h A$.

Theorem: Java is type safe (continued)

- (abr1)** If $restbody^*/\alpha = Break(l)$, then α is in a statement with label l and $body(meth^*)/\alpha$ contains a **reachable** break lab which **can exit** $body(meth^*)/\alpha$.
- (abr2)** If $restbody^*/\alpha = Continue(l)$, then α is in a while statement with label l .
- (abr3)** If $restbody^*/\alpha = Return$, then α is in the body of a method with return type `void`.
- (abr4)** If $restbody^*/\alpha = Return(v)$, then α is in the body of a method with return type A and v is a value of type $B \sqsubseteq A$.
- (abr5)** If $restbody^*/\alpha = Exc(ref)$, then $classOf(ref) = E$, $E \preceq_h Throwable$, E is **allowed** at position α and $body(meth^*)/\alpha$ **can throw** an exception F such that $E \preceq_h F$.

Theorem: Java is type safe (continued)

Assume that $(_, restbody^*, \beta, _)$ is the parent frame of $(c/m, _, _, locals^*)$ in state n of thread q . Then the dynamic method invocation chain has the following properties:

(chain1) If the return type of c/m is A and $A \neq \text{void}$, then $\mathcal{T}(\beta) = A$.

(chain2) If E occurs in the throws clause of c/m , then E is allowed at position β .

(chain3) If c/m is a constructor and $restbody^* / \beta = ref.c/m(_)$, then $locals^*(\text{this}) = ref$.

Theorem: Java is type safe (continued)

The following global invariants are true in state n :

(global) If c/f is a static field of declared type A , then $globals_n(c/f)$ is a value of type $B \sqsubseteq A$.

(ref) If a reference ref is used in state n , then $ref \in dom(heap_n)$.

(object1) If $heap_n(ref) = Object(c, fields)$, then c is a non abstract class and $dom(fields) = instanceFields(c)$.

(object2) If $heap_n(ref) = Object(_, fields)$, $fields(f) = v$ and f is of declared type A , then v is a value of type $B \sqsubseteq A$.

(array) If $heap_n(ref) = Array(A, elems)$ and $elems(i) = v$, then v is a value of type $B \sqsubseteq A$.