



UNIVERSITÀ DI PISA

# FORMALIZING ROBUSTNESS OF BIOCHEMICAL NETWORKS

DataMod 2018  
(Toulouse, France)

.....

**Lucia Nasti**

*lucia.nasti@di.unipi.it*

**Roberta Gori**

*gori@di.unipi.it*

**Paolo Milazzo**

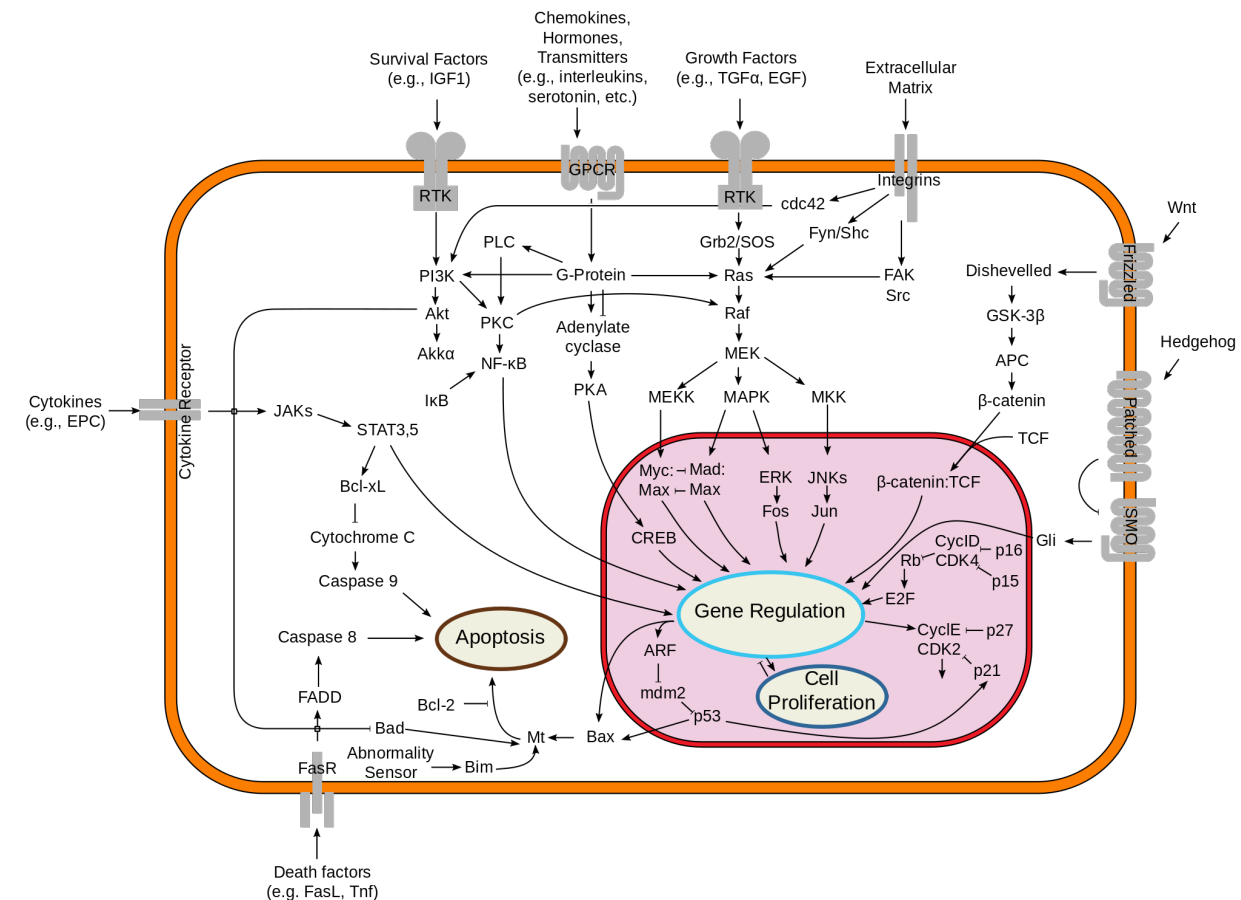
*milazzo@di.unipi.it*





# BACKGROUND

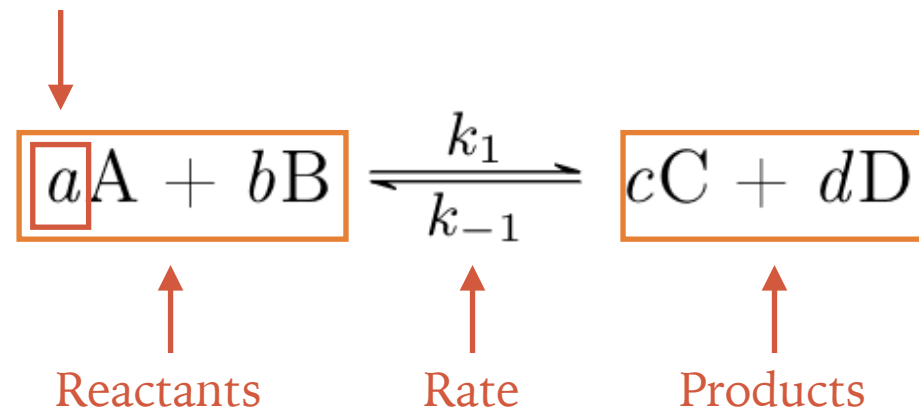
- A cell is a **very complex system**
- Chemical reaction networks (**pathways**) govern the basic cell's activities
- To examine the structure of the cell as a whole, we can design **multiscale and predictive models**



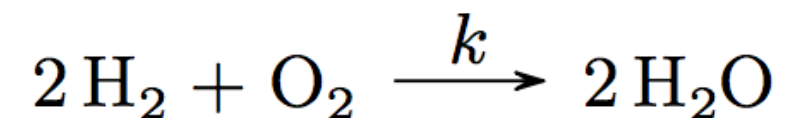
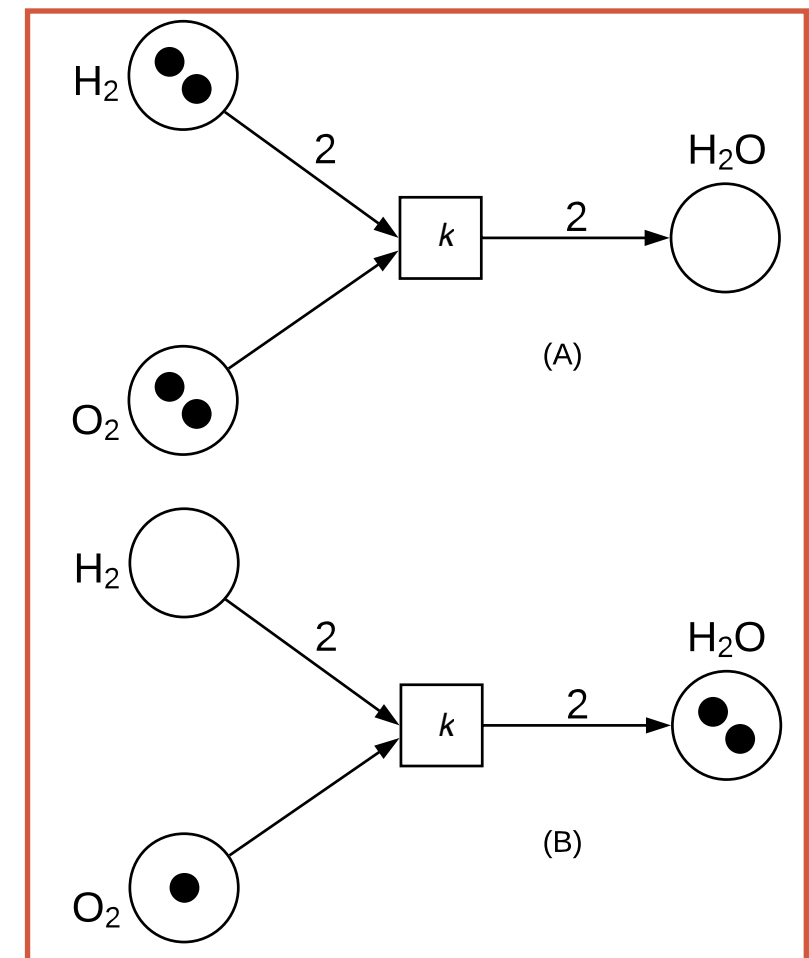
Experiments *in vitro* ↔ Experiments *in silico*

# CHEMICAL REACTIONS

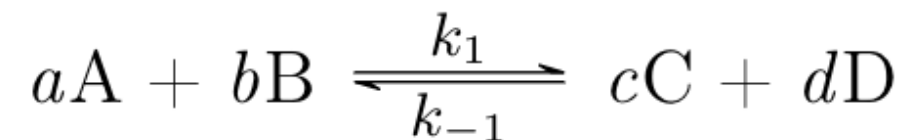
Stoichiometric coefficient



- **Kinetic rate:** rate of a reaction
- **Reactant:** chemical species that is consumed
- **Product:** chemical species that is created
- **Stoichiometric coefficient:** the number of species involved in the reaction
- **Concentrations:**  $[A]$ ,  $[B]$ ,  $[C]$ ,  $[D]$



# CHEMICAL KINETICS



- **Law of mass action:** reaction rate is proportional to the reactants product

$$r \propto [\text{reactants}] \longrightarrow r = k_1 [A]^a [B]^b$$

$$r_{\text{direct}} = r_{\text{inverse}}$$

$$\begin{aligned} \frac{d[A]}{dt} &= \overbrace{-ak_1[A]^a[B]^b}^{\text{direct reaction term}} \overbrace{+ak_{-1}[C]^c[D]^d}^{\text{inverse reaction term}} \\ \frac{d[B]}{dt} &= -bk_1[A]^a[B]^b + bk_{-1}[C]^c[D]^d \\ \frac{d[C]}{dt} &= +ck_1[A]^a[B]^b - ck_{-1}[C]^c[D]^d \\ \frac{d[D]}{dt} &= +dk_1[A]^a[B]^b - dk_{-1}[C]^c[D]^d \end{aligned}$$

# ROBUSTNESS PROPERTY

---

- Our goal: to define **robustness** property
- **Robustness** allows the system to preserve its functions despite internal and external perturbations

In nature, there are **different mechanisms** ensuring this property:

- Modularity
- System control
- Redundancy
- Structural stability

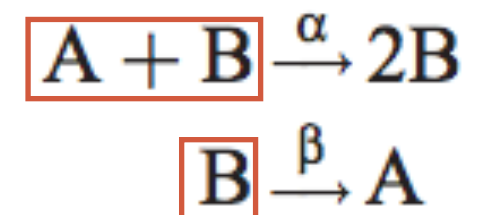
# ROBUSTNESS IN LITERATURE

---

- Many definitions, which find *sufficient conditions* for **particular biochemical networks**
- In [Shinar-Feinberg]:

The **sufficient condition** states that a mass action system can be considered robust if it admits a positive steady state, the underlying reaction network has a **deficiency=1** and there are distinct non-terminal complexes that differ only in a single species.

*deficiency = number of nodes - linkage classes - rank.*



- In [Barkai-Leibler]:

A system is robust only if its operation does not depend on initial concentration of chemical species involved. Introduction of **degree** in robustness

# OUR PROPOSAL

---

- Formal definition of robustness property
- Analyse systems with deficiency  $> 1$
- Execution of the system by simulations
- Analyse robustness degree

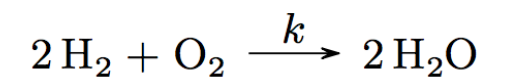
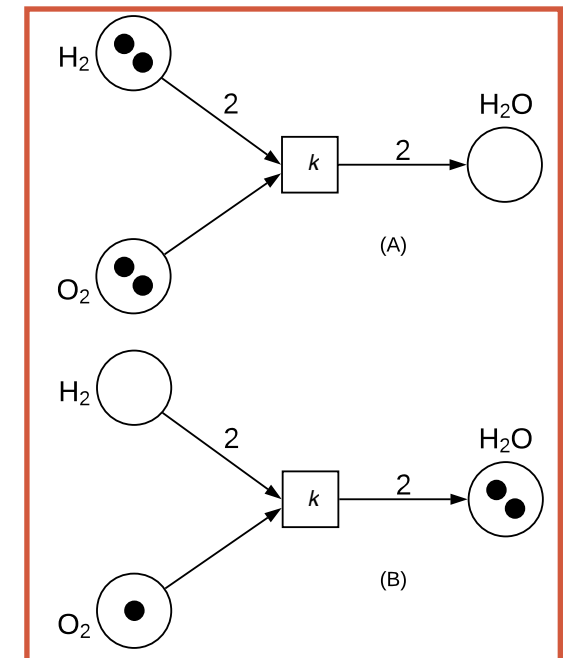
# CONTINUOUS PETRI NETS FORMALISM DEFINITION

A continuous Petri net  $N$  is a quintuple:

$$N = \langle P, T, F, W, m_0 \rangle$$

where:

- $P$  is the set of continuous *places*, conceptually species
- $T$  is the set of continuous *transitions*, that consume and produce species
- $F \subseteq (P \times T) \cup (T \times P) \rightarrow \mathbb{R}_{\geq 0}$  represents the set of arcs in terms of a function giving the weight of the arc as result: a weight equal to 0 means that the arc is not present
- $W : T \rightarrow \mathbb{R}_{\geq 0}$  is a function, which associates each transition with a *rate*
- $m_0$  is the *initial marking*, that is the initial distribution of *tokens* (representing resource instances) among places. A marking is defined formally as  $m : P \rightarrow \mathbb{R}_{\geq 0}$





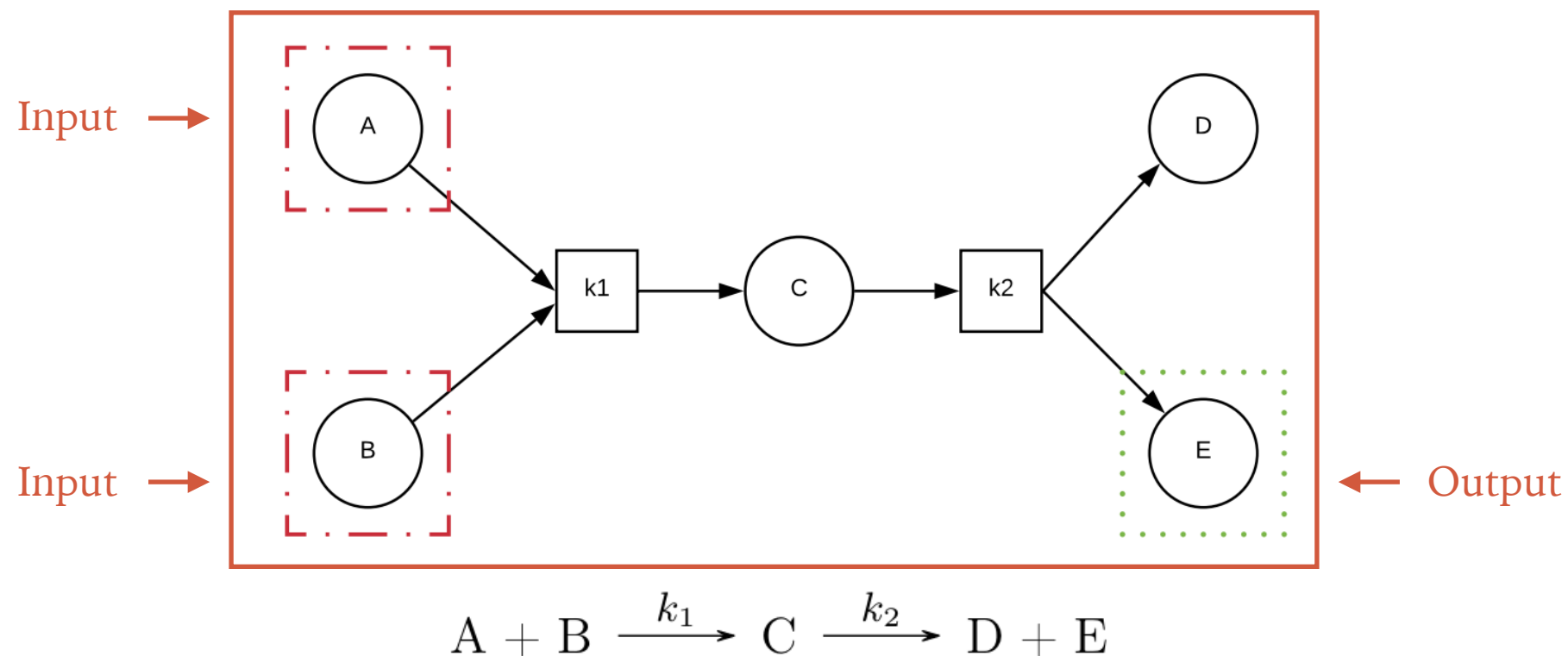
# FORMAL DEFINITION OF ROBUSTNESS: AUXILIARIES CONCEPTS

- **Definition 1 (Intervals).** We define the interval domain

$$I = \{[n, m] \mid n, m \in \mathbb{R}_{\geq 0} \cup \{+\infty\} \text{ and } n \leq m\}$$

Moreover we say that  $x \in [n, m]$  iff  $n \leq x \leq m$ .

- **Definition 2 (Interval marking).** An interval marking is a function  $m_{[\ ]} : P \rightarrow I$ . We call  $M_{[\ ]}$  the domain of all interval markings.



# FORMAL DEFINITION OF ROBUSTNESS

---

- **Definition 3 ( *$\alpha$ -Robustness*)**. A Petri net PN with output place  $O$  is defined as  *$\alpha$ -robust* with respect to a given marking  $m_{[]}$  iff  $\exists k \in \mathbb{R}$  such that  $\forall m \in m_{[]}$ , the marking  $m'$  corresponding to the steady state reachable from  $m$ , is such that

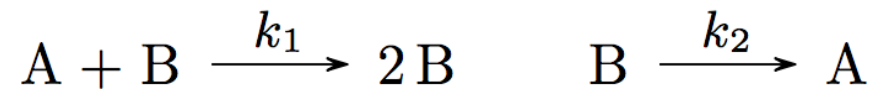
$$m'(O) \in [k - \frac{\alpha}{2}, k + \frac{\alpha}{2}]$$

## Observations:

- wider are the intervals of the initial interval marking, more robust is the network
- smaller is the value of  $\alpha$ , more robust is the network

# EXAMPLE OF APPLICATION OF OUR DEFINITION : TOY MODEL

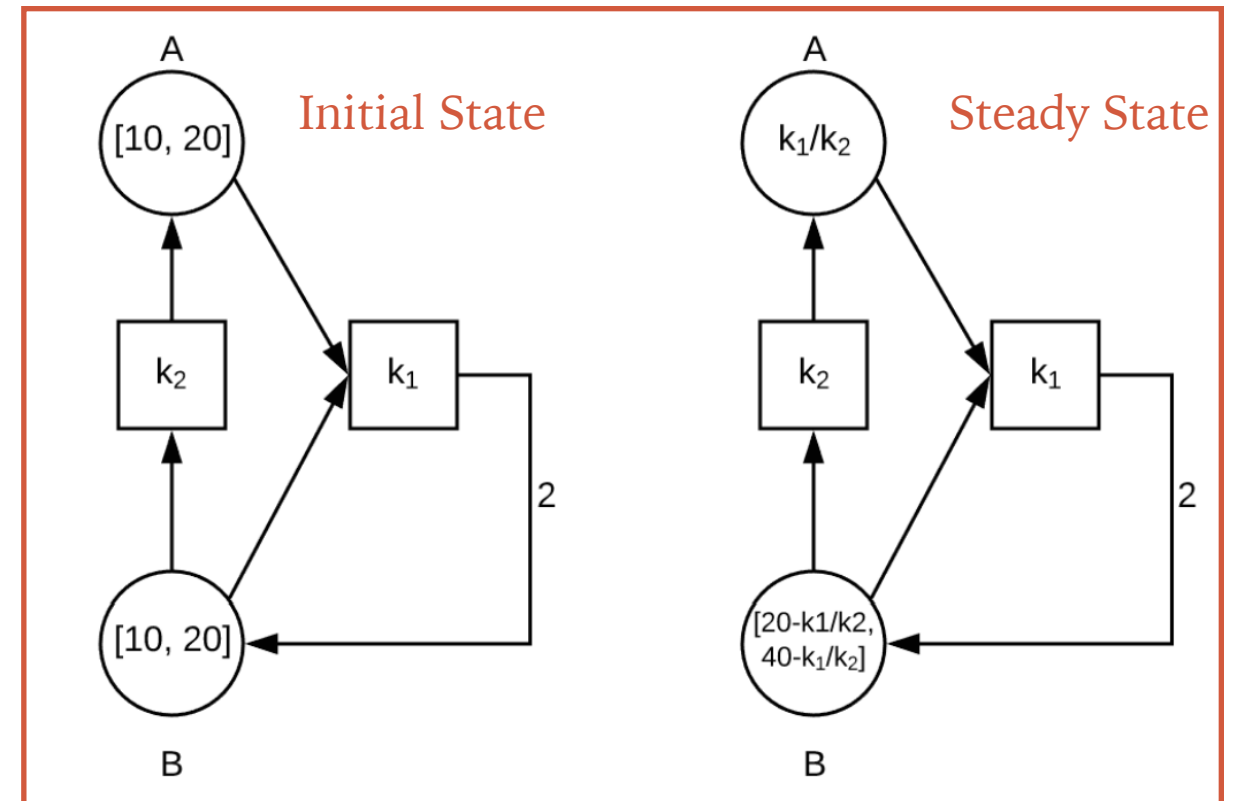
Given a set of chemical reactions:



We calculate the concentration of chemical species **at the steady state**:

$$A = \frac{k_2}{k_1} \quad B = \theta - \frac{k_2}{k_1}$$

where  $\theta$  is the sum of initial concentrations of A and B.



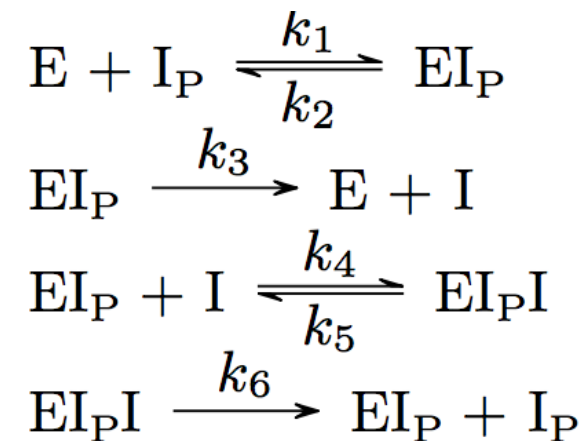
We apply the definition: for A we obtain  $a=0$ . For B we obtain  $a=20$ , because:

$$B = [20 - \frac{k_2}{k_1}, 40 + \frac{k_2}{k_1}]$$

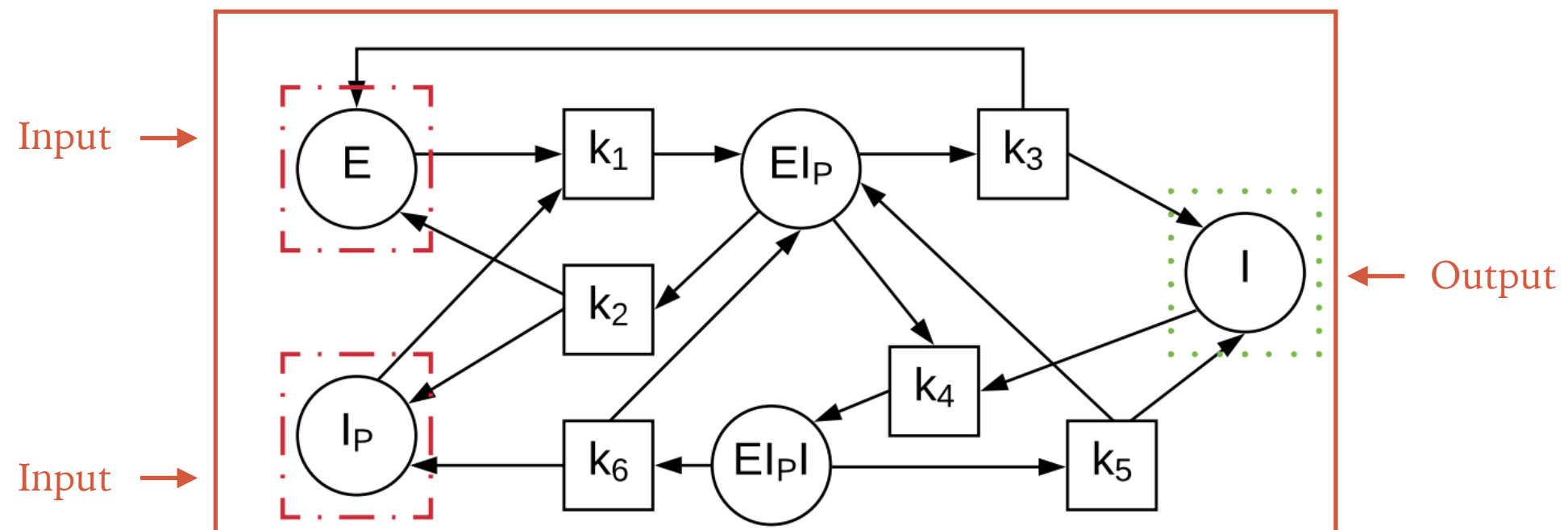
# EXAMPLE OF APPLICATION OF OUR DEFINITION : IDHKP-IDH

---

- Given a set of reactions:



- We build the Petri nets and choose input and output

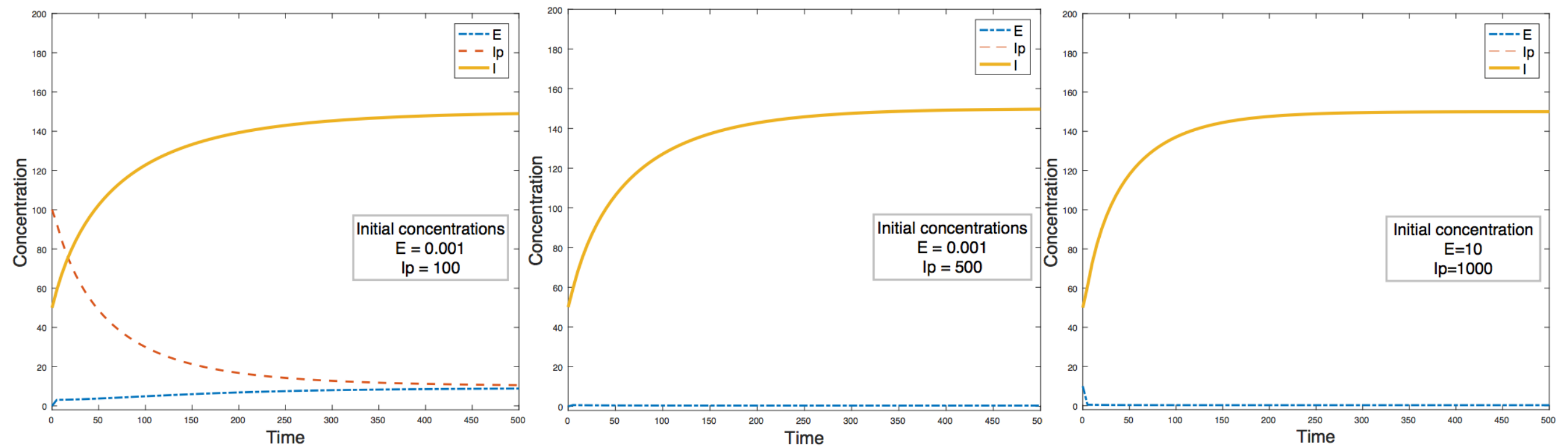




# IDHKP-IDH: SIMULATION RESULTS

---

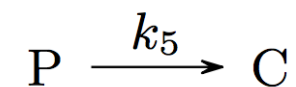
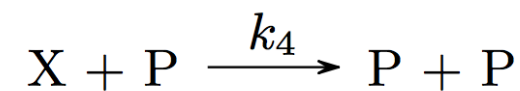
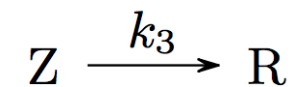
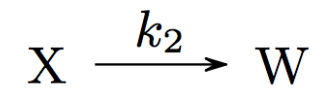
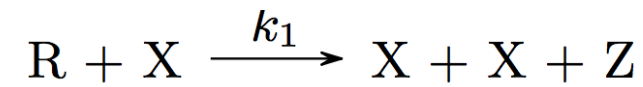
We vary the **initial concentration of the inputs** ( $[I_p]$  and  $[E]$ ) and we obtain exactly the same concentration value for  $[I]$ . Hence,  $a=0$ .



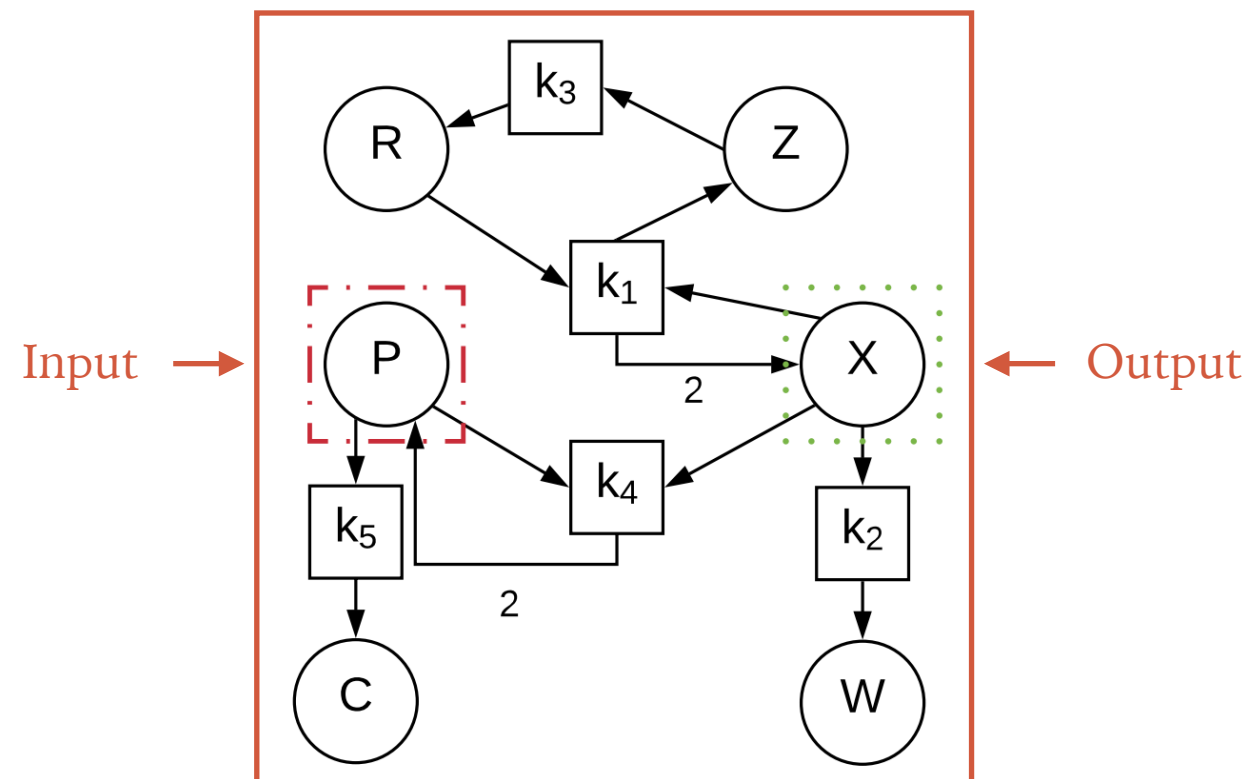
# EXAMPLE OF APPLICATION OF OUR DEFINITION : ENZYME ACTIVITY

---

- Given a set of reactions:



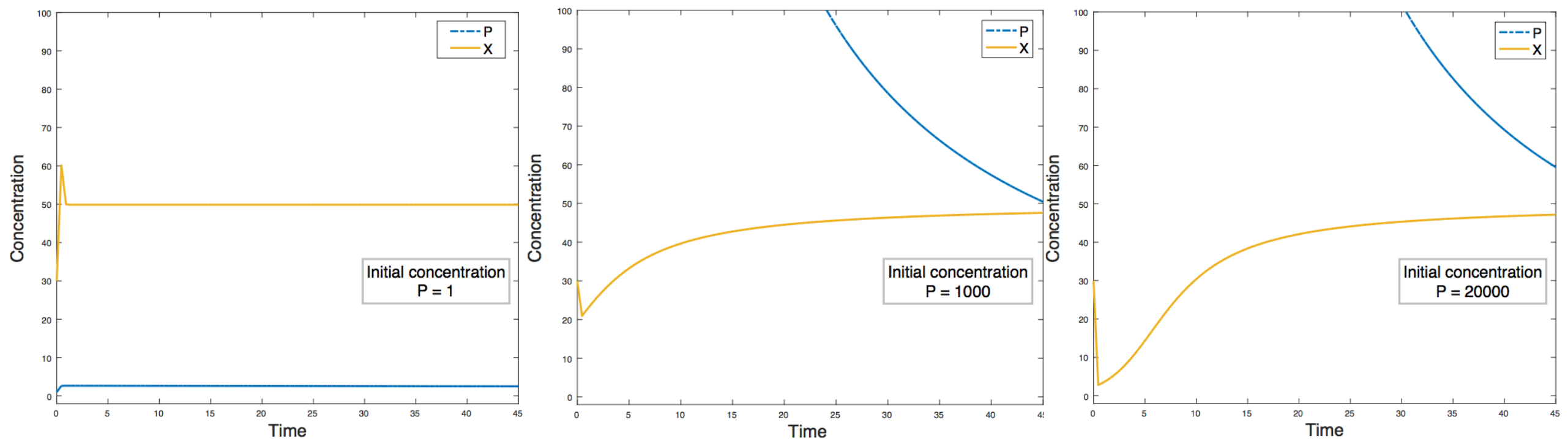
- We build the Petri nets and choose input and output



# ENZYME ACTIVITY AT SATURATION: SIMULATION RESULTS

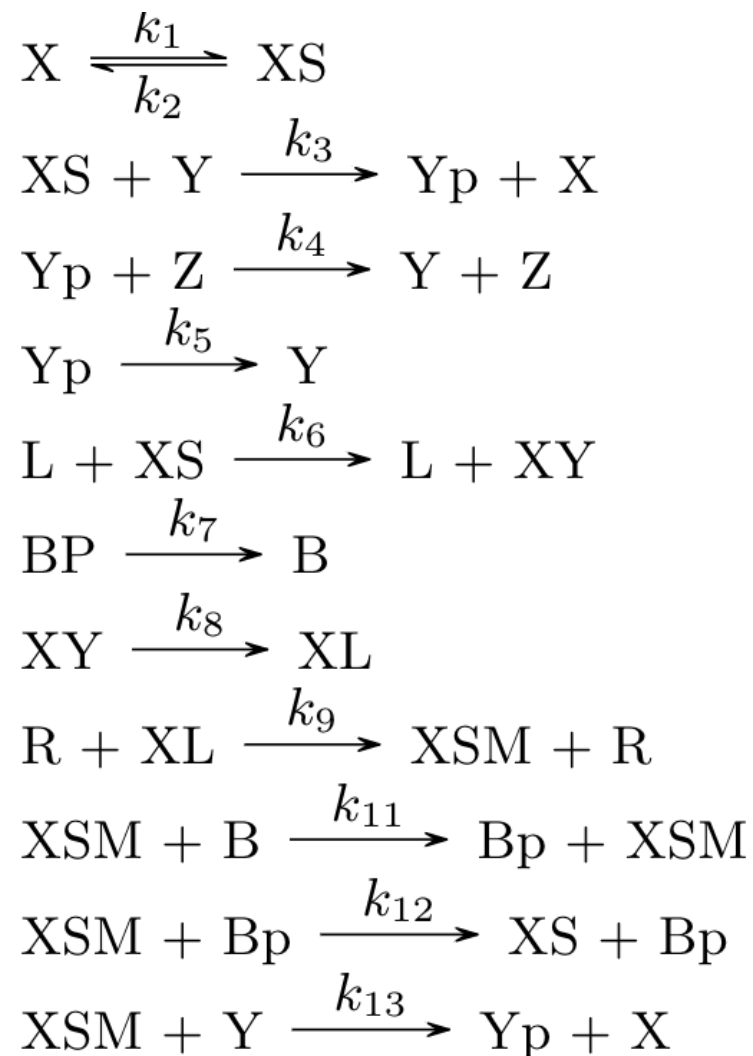
---

We vary the **initial concentration of the inputs** ( $[P]$ ) and we obtain these concentrations for the species  $[X]$ . Hence, we obtain  $a=3$ .

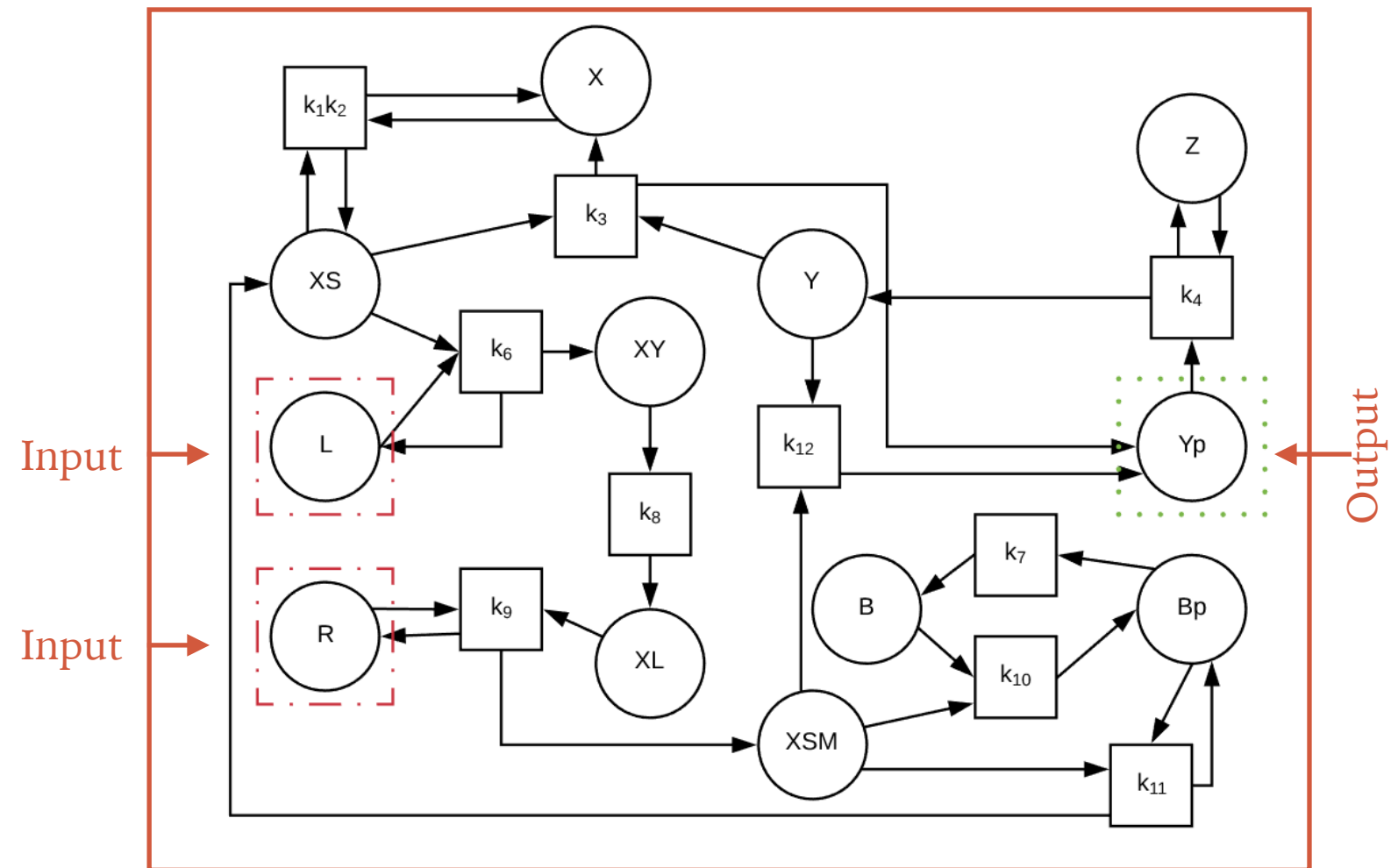


# EXAMPLE OF APPLICATION OF OUR DEFINITION : CHEMOTAXIS OF E. COLI

➤ Given a set of reactions:



➤ We build the Petri net:

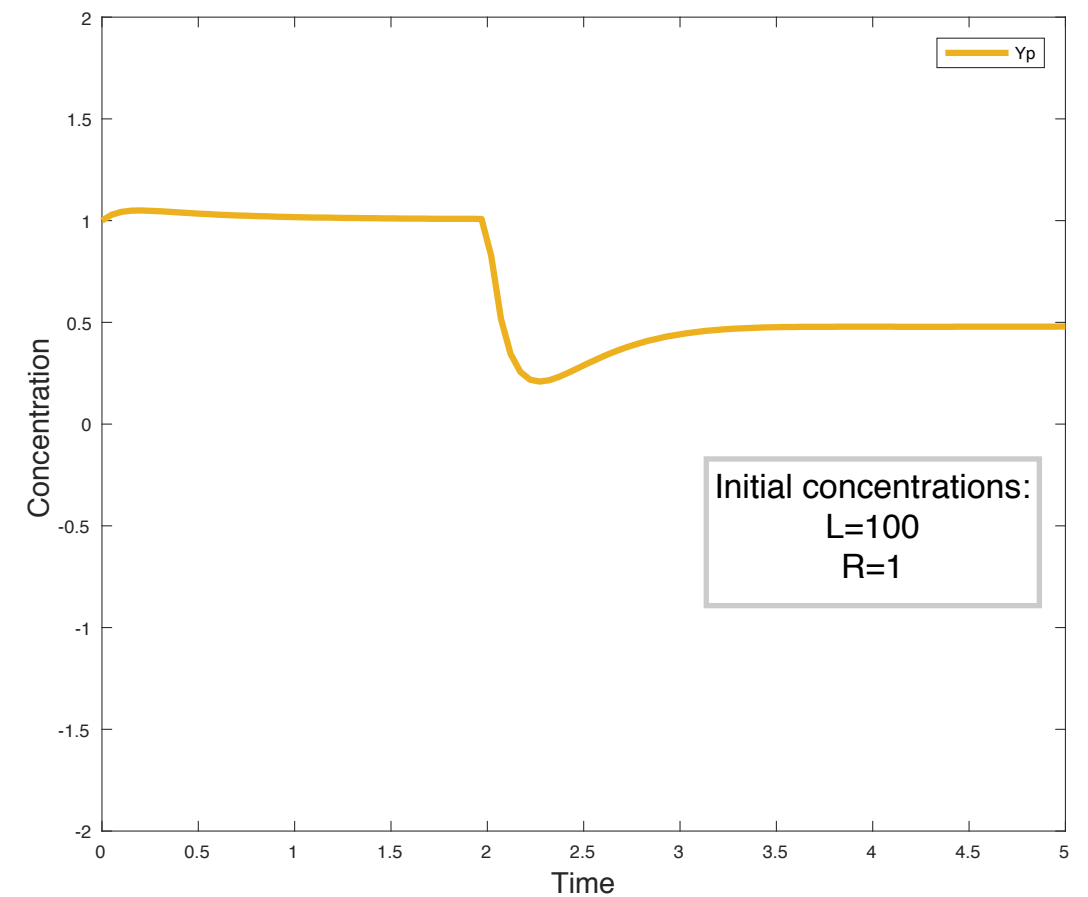
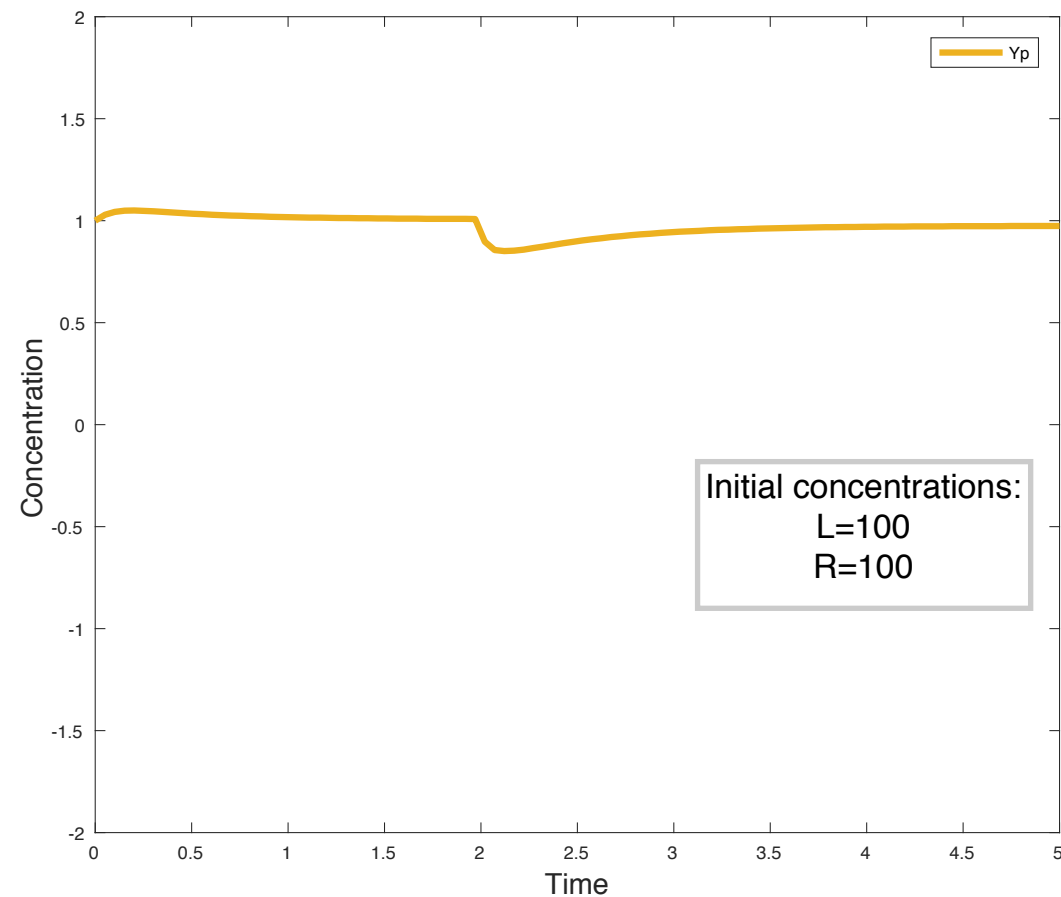




# CHEMOTAXIS OF E.COLI: SIMULATION RESULTS

---

We vary the **initial concentration of the inputs** ( $[R]$ ) and we obtain these concentrations for the species  $[Y_p]$ . Hence, we obtain  $a=0.5$



# CONCLUSIONS

---

- Formal definition of robustness property
- Definition able to capture different kind of robustness
- Analysis of the system by simulations

Future work:

- Analyse **monotonicity** of the system
- Find a **sufficient condition** limiting the computational effort





# QUESTIONS?

*thank you!*