

# Intermediate Representations

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# Where are we?

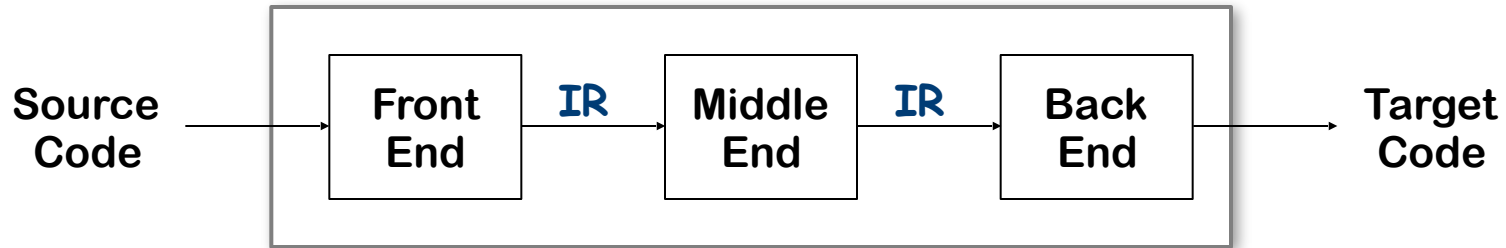
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- We are on the cusp of the art, science, & engineering of compilation
- Scanning & parsing are applications of automata theory
- Context-sensitive analysis, as covered in class, is mostly software engineering
- The mid-section of the course will focus on issues where the compiler writer needs to choose among alternatives
  - The choices matter; they affect the quality of compiled code
  - There may be no “best answer” or “best practice”

The fun begins at this point

# Intermediate Representations

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- Front end - produces an intermediate representation (IR)
- Middle end - transforms the IR into an equivalent IR that runs more efficiently
- Back end - transforms the IR into native code
- IR encodes the compiler's knowledge of the program
- Middle end usually consists of several passes

# Intermediate Representations

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- Decisions in IR design affect the speed and efficiency of the compiler
- Some important IR properties
  - Ease of generation
  - Ease of manipulation
- The importance of different properties varies between compilers
  - Selecting an appropriate IR for a compiler is critical
- Three axes of choice: structural organization, level of abstraction, naming discipline

# Structural organization

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## Three major categories

- Structural
  - Graphically oriented
  - Heavily used in source-to-source translators
  - Tend to be large
- Linear
  - Pseudo-code for an abstract machine
  - Level of abstraction varies
  - Simple, compact data structures
  - Easier to rearrange
- Hybrid
  - Combination of graphs and linear code

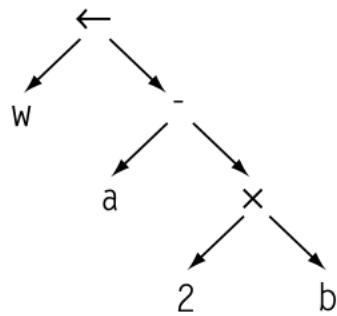
Examples:  
Trees, DAGs

Examples:  
3 address code  
Stack machine code

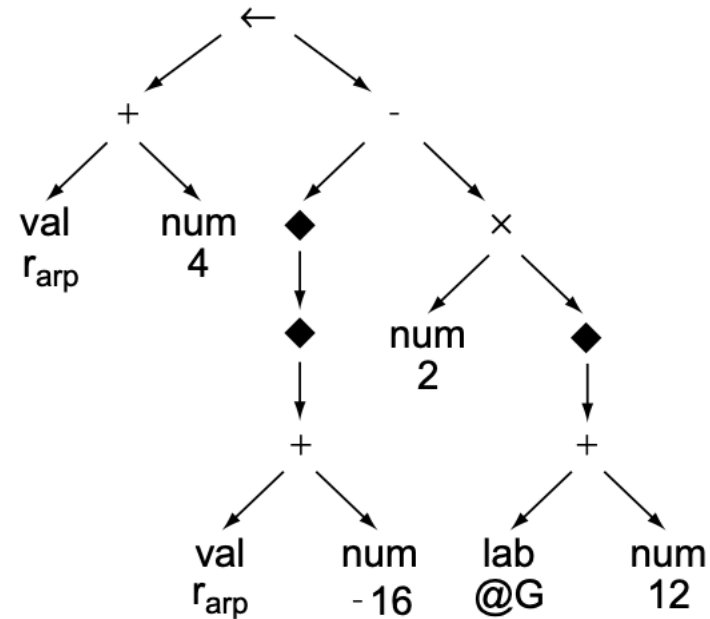
Example:  
Control-flow graph

# AST with different level of abstraction

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(a) Source-Level AST

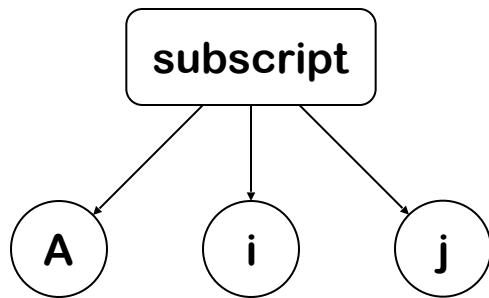


(b) Low-Level AST

# Level of Abstraction

- The level of detail exposed in an IR influences the profitability and feasibility of different optimizations.
- Two different representations of an array reference:

array  $A[1..10,1..10]$  of 1 byte memorised in row-major order



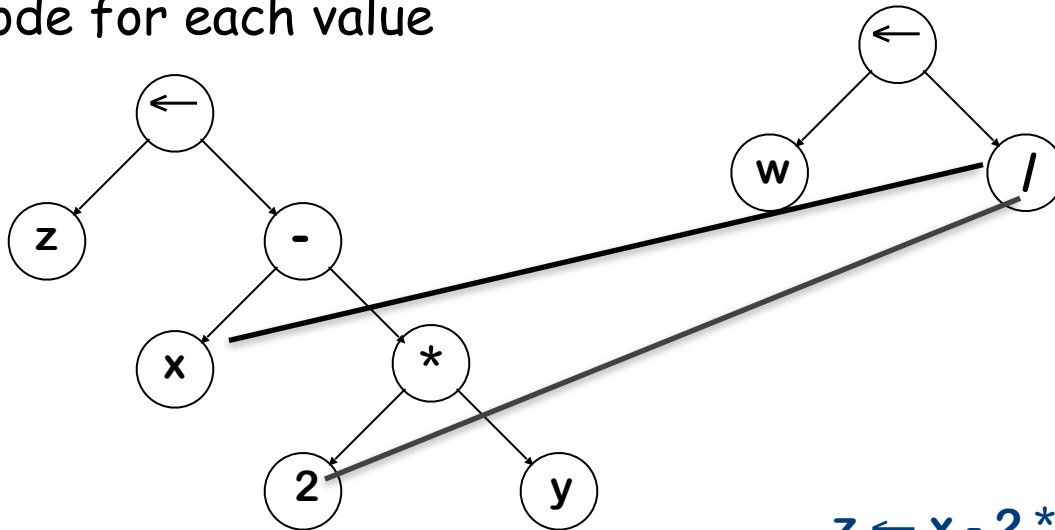
High level AST:  
Good for memory  
disambiguation

```
loadI 1      => r1
sub    rj, r1 => r2
loadI 10     => r3
mult   r2, r3 => r4
sub    ri, r1 => r5
add    r4, r5 => r6
loadI @A     => r7
add    r7, r6 => r8
load   r8     => rAij
```

Low level linear code:  
Good for further optimisation

# Directed Acyclic Graph

A directed acyclic graph (DAG) is an AST with a unique node for each value



$z \leftarrow x - 2 * y$   
 $w \leftarrow x / 2$

- Makes sharing explicit
- Encodes redundancy

With two copies of the same expression, the compiler might be able to arrange the code to evaluate it only once.



## The third axis : naming

- The compiler must choose names for a variety of distinct values.

•  $a - 2 * b$        $t1 \leftarrow b$   
                          $t2 \leftarrow 2 * t1$   
                          $t3 \leftarrow a$   
                          $t4 \leftarrow t3 - t2$        $t1, t2, t3$  and  $t4$  are new names

If every subexpression has a name the compiler can reuse the value of the subexpression

# Naming :Stack Machine Code

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Originally used for stack-based computers, now Java

- Example:

$x - 2 * y$

becomes

```
push x
push 2
push y
multiply
subtract
```

## Advantages

- Compact form
- Introduced names are implicit, not explicit
- Simple to generate and execute code

Useful where code is transmitted  
over slow communication links (the net)

Implicit names take up  
no space, where explicit  
ones do!

# Three Address Code

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Several different representations of three address code

- In general, three address code has statements of the form:

$$x \leftarrow y \text{ op } z$$

With 1 operator (op) and, at most, 3 names (x, y, & z)

Example:

$z \leftarrow x - 2 * y$  becomes

$t \leftarrow 2 * y$   
 $z \leftarrow x - t$

Advantages:

- Resembles many real machines
- Introduces a new set of names
- Compact form

# Three Address Code: Quadruples

Naïve representation of three address code

- Table of  $k * 4$  small integers
- Simple record structure
- Easy to reorder
- Explicit names

The original FORTRAN compiler used "quads"

```
load  r1, y
loadI r2, 2
mult  r3, r2, r1
load  r4, x
sub   r5, r4, r3
```

RISC assembly code

load	1	y	
loadi	2	2	
mult	3	2	1
load	4	x	
sub	5	4	3

Quadruples

# Three Address Code: Triples

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- Index used as implicit name
- 25% less space consumed than quads
- Much harder to reorder

(1)	load	y	
(2)	loadI	2	
(3)	mult	(1)	(2)
(4)	load	x	
(5)	sub	(4)	(3)

```
load  r1, y
loadI r2, 2
mult  r3, r2, r1
load  r4, x
sub   r5, r4, r3
```

Implicit names occupy no space

Remember, for a long time, 640Kb was a lot of RAM

- Major tradeoff between quads and triples is compactness versus ease of manipulation
  - In the past compile-time space was critical
  - Today, speed may be more important

# Two Address Code

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- Allows statements of the form

$$x \leftarrow x \text{ op } y$$

Has 1 operator (op) and, at most, 2 names (x and y)

Example:

$$z \leftarrow x - 2 * y$$

becomes

$$t_1 \leftarrow 2$$

$$t_2 \leftarrow \text{load } y$$

$$t_2 \leftarrow t_2 * t_1$$

$$z \leftarrow \text{load } x$$

$$z \leftarrow z - t_2$$

- Can be very compact

Problems

- Machines no longer rely on destructive operations
- Difficult name space
  - Destructive operations make reuse hard
  - Good model for machines with destructive ops (PDP-11)

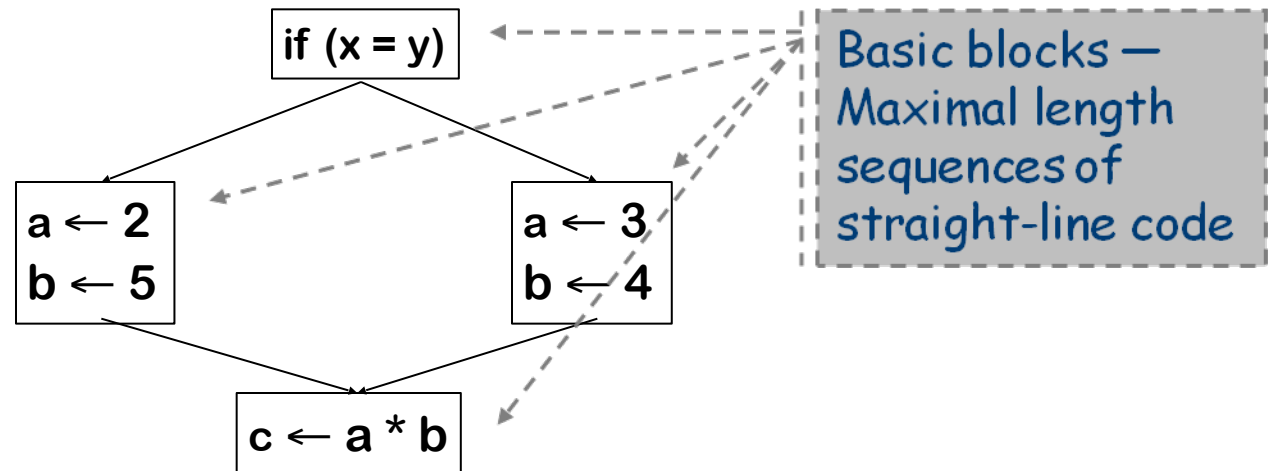
# Control-flow Graph

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Models the transfer of control in the procedure

- Nodes in the graph are basic blocks
  - Can be represented with quads or any other linear representation
- Edges in the graph represent control flow

Example



# Static Single Assignment Form

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- The main idea: *each name is defined exactly once*
- The name refers to the variable in some program point
- Encodes both control and value flow
- Introduce  $\phi$ -functions to make it work

## Original

```
x ← ...
y ← ...
while (x < k)
  x ← x + 1
  y ← y + x
```

## SSA-form

```
x0 ← ...
Y0 ← ...
if (x0 >= k) goto next
loop:
  x1 ←  $\phi(x_0, x_2)$ 
  Y1 ←  $\phi(Y_0, Y_2)$ 
  x2 ← x1 + 1
  Y2 ← Y1 + x2
  if (x2 < k) goto loop
next:
  ...
```

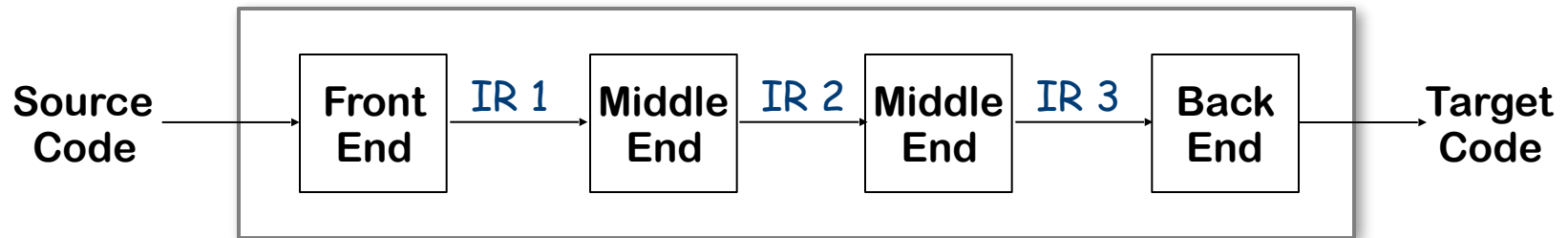
## Strengths of SSA-form

- each use refers to a single definition
- (sometimes) faster algorithms



# Using Multiple Representations

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- Repeatedly lower the level of the intermediate representation
  - Each intermediate representation is suited towards certain optimizations
- Example: the Open64 compiler
  - WHIRL intermediate format
    - Consists of 5 different IRs that are progressively more detailed and less abstract

# Memory Models

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## Two major models

- Register-to-register model
  - Keep all values that can legally be stored in a register in registers
  - Ignore machine limitations on number of registers
  - Compiler back-end must insert loads and stores
- Memory-to-memory model
  - Keep all values in memory
  - Only promote values to registers directly before they are used
  - Compiler back-end can remove loads and stores
- Compilers for RISC machines usually use register-to-register
  - Easier to determine when registers are used

use virtual registers!

# The Rest of the Story...

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Representing the code is only part of an IR

The compiler must discover and store many distinct kinds of information

For a variable it has to store its data type, storage class, the level of its declaring procedure, and a base and offset in memory

For an array also the number of dimension and the upper and lower bounds of each dimension

It often uses centralised information

- Symbol table
- Constant table

It needs an efficient and expandable way to realise them!

# Symbol Tables

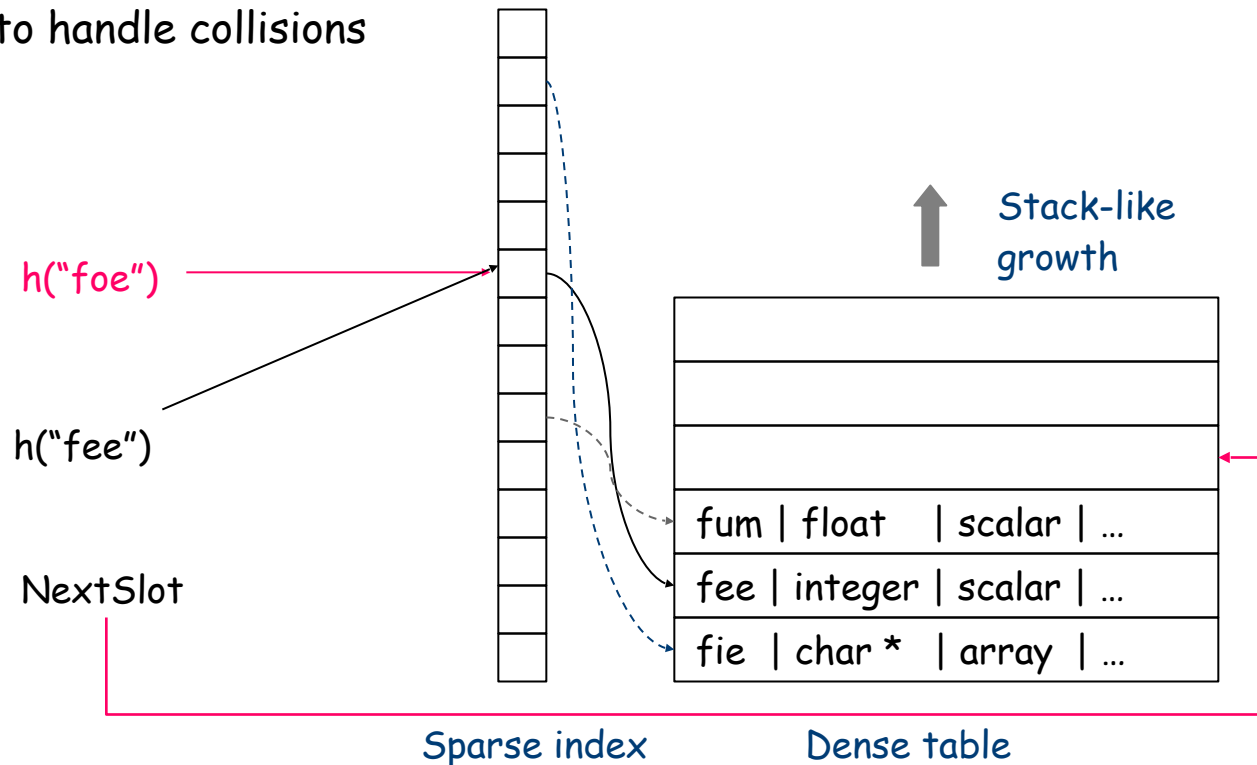
Classic approach uses hashing because we need a constant-time expected lookup

A two-table scheme

- Sparse index to reduce chance of collisions
- Dense table to hold actual data
  - Easy to expand, to traverse, to read & write from/to files

- Use chains in index to handle collisions

Collision occurs when  $h()$  returns a slot in the sparse index that is already full.



# Hash-less Symbol Tables

Classic approach to building a symbol table uses hashing

- Some concern about worst-case behavior
  - Collisions in the hash function can lead to linear search
  - Some authors advocate “perfect” hash for keyword lookup

Collision occurs when  $h()$  returns a slot in the sparse index that is already full.

