XPath

Expressivity of XPath

FO-XPath

- · We add:
 - $-id(p/@A): {< m,n> | m p/@A m' and n/@ID = m' }$
 - p/@A RelOp i: existential semantics
 - p/@A RelOp q/@B: existential semantics
- · Integers i are just constants

Reference

 XPath leashed, Michael Benedikt and Christoph Koch, TR, 2006

Formal setting

- XPath interpreted in a logical structure t with a finite set of labels and a finite set of Attributes @Ai (functions from nodes to integers)
- Navigational XPath:
 - $p ::= step | p/p | p \lor p$
 - step ::= axis | step[q]
 - $-q := lab() = L | p | q \land q | q \lor q |$ **not q**
- · Semantics:
 - [[p]]t: Node -> P(Node) (= NodeSet)
 - -[[q]]t: Node -> Bool

AggXPath

- Integers are extended with aggregates and arithmetic:
 - $-i ::= 'c' \mid i+i \mid i*i \mid count(p) \mid sum(p/@A)$
- · Comparisons are extended with i RelOp j
- AggXPath with positions (OrdXPath):
 - We add position() and last():
 - i ::= ... | position() | last()
 - Qualifiers are evaluated wrt to a context enriched with the position of the current element and the length of its sequence

Restrictions:

- P-X-XPath: no negation or disequality
- Conjunctive query: positive, no disjunction, no union

Expressiveness

 NavXPath can be translated in linear time as FO over Lab_L, R_axis where axis in: child, next-sibl, desc, foll-sibl:

(x,y) in book[title]/author:

 $\exists z,w. \ child(x,z) \land Lab_book(z) \land child(z,w) \land \\ < title>(w) \land child(z,y) \land < author>(y)$

(x,y) in parent::(book)/child::author:

 $\exists z. \ child(z,x) \land <book>(z) \land child(z,y) \land <author>(y)$

NavXPath vs. FO

- FO is more expressive:
 - Exists a subsequence C-B*-C?
- NavXPath = FO²:
 - qualifiers in NavXPath corresponds to FO² (2-variables FO) with one free variable
 - NavXPath paths have a linear normal form

NavXPath and FO²

- XPNF:
 - $\begin{array}{l} \ \exists z_2 \ldots \exists z_{n-1}. \ \rho_1(z_1) \land \chi_1(z_1, \, z_2) \land \rho_2(z_2) \land \ldots \land \\ \chi_{n-1}(z_{n-1}, \, z_n) \land \rho_n(z_n) \end{array}$
 - ρ_{i} are FO² formulas, and the $\chi_{i-1}(z_{i-1},\,z_{i})$ are unions of binary atomic formulas over predicates from child, next-sibl, desc, foll-sibl
- Theorem:
 - NavXPath filters correspond to FO2 formulas
 - NavXPath relations correspond to expressions in XPNF
- Key observation: any boolean combination of steps, equality, inequality can be reduced to a union of steps

Proof

- Key case: translate ∃y β(x, y), where β is in FO2 into qualifiers
- Bring β in DNF; every disjunct contains some binary axes (including equality), maybe negated, and two unary FO2 formulas
- Since axes are mutually exclusive, we can assume that every disjunct is just:
 - $\varphi i(x) \wedge R\chi i(x, y) \wedge \psi i(y)$
- · Which becomes
 - self[T(φi)]/χi[T(ψi)]

Closure of NavXPath

- NavXPath includes union
- NavXPath is closed under intersection:
 - A NavXPath query is conjunctive
 - Conjunctive queries are intersection-closed
 - Conjunctive queries over trees can be transformed into unions of acyclic conjunctive queries
 - These can be expressed by NavXPath

Closure of NavXPath

- NavXPath predicates are closed under complement
- NavXPath relations are not closed under complement
- · Proof sketch:
 - with complement we can express Until (actually, all of FO)
 - NavXPath cannot express Until
- A until B (where ∧ and not are relational):
 - desc[lab = B] \wedge not(desc[lab != A]/desc)

NavXPath and tree patterns

- Tree patterns: node- and edge-labeled trees
- Edges are labeled with forward axes
- Nodes are labeled with either L or *
- Boolean TP: one context node
- Unary TP: context node + selected node

Matching a tree pattern

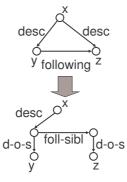
- Boolean: a homomorphism from the pattern to the tree, that maps the context into the node
- Unary: context is mapped into the first node, selected into the second
- Finite set of TPs: take the union of the results

TPs and NavXPath

- · The following are equally expressive:
 - P-NavXPath binary queries
 - Sets of unary patterns
 - Exists+ FO with child, next-sibl, desc, followingsibl
- (1) and (2) into (3) is immediate
- TP to XPath: every edge is a step
- FO to TP: form the formula graph, then remove the cycles (non trivial!)

From Ex+ FO to TP

- Ex+ FO is the same as union of (cyclic) conjunctive queries:
 - $-\exists y.desc(x,y), desc(x,z), following(y,z)$
- Every cycle can be rewritten out



Some rules

- d-o-s(x,z),d-o-s(y,z) ->
 - $d-o-s(x,z),d-o-s(y,x) \lor d-o-s(x,y),d-o-s(y,z)$
 - Same for foll-sibl
- child(x,z),d-o-s(y,z) ->
 - (child(x, z) \land y = z) \lor (child(x, z) \land d-o-s(y, x))
 - Same for next-sibl / foll-sibl
- next-sibl(x,z),d-o-s(y,z)
 - $\; (\text{next-sibl}(\textbf{x},\textbf{z}) \land \textbf{y} = \textbf{z}) \lor (\text{next-sibl}(\textbf{x},\,\textbf{z}) \land \text{desc}(\textbf{y},\,\textbf{x}))$
 - Same for NS+, NS*

TP, Ex+, and P-NavXPath

- From the previous theorem, a couple of nice corollaries about P-NavXPath:
 - Using EX-+: P-NavXPath is closed under ...?
 - Using TP: only forward axes are needed for positive root-queries (Olteanu et al 2002)

Extending XPath to FO

- · Add path complement
- Add Until

Back to FO-XPath

- · We add:
 - -id(p/@A): i nodi n tali che n/@ID = p/@A
 - i RelOp i
 - p/@A RelOp i: existential semantics
 - p/@A RelOp q/@B: existential semantics
- Easy to translate in FO with the obvious signature (Ai-Comp-Aj(x,y) + transnavigation)
- Is FO-XPath complete for FO?

Weakness of FO-XPath

- Navigational query: does not depend on attributes, but just on the tree structure
- FO-XPath expresses the same navigational queries as NavXPath

Back to Agg-XPath

- Integers are extended with aggregates and arithmetic:
 - $-i := c' \mid i+i \mid i*i \mid count(p) \mid sum(p/@A)$
- · Count can express Until
- · Hence: FO complete
- Until(E2,E1) (where desc is not reflexive):
 - desc[E2] and count(desc[not E1]/desc[E2]) != count(desc[E2])

Complexity of evaluation

Complexity: reminder

- Some classes I may name, and their relationship
 - LOGSPACE ⊆ PTIME ⊆ PSPACE ⊆ EXPTIME
 - $\begin{aligned} \operatorname{LOGSPACE} &\subseteq \operatorname{NLOGSPACE} &\subseteq \operatorname{P}(\operatorname{TIME}) \\ &\subseteq \operatorname{NP}(\operatorname{TIME}) &\subseteq \operatorname{PSPACE} &\subseteq \operatorname{EXPTIME} \end{aligned}$
 - $-P \subseteq co-NP \subseteq PSPACE$
- Non-elementary: not bounded by 2⁽²...(2ⁿ))

Data complexity and combined complexity

- Assume that the evaluation of a query Q on a structure T costs: O(|T|^|Q|)
- · How bad is that?
 - Data complexity: it is in PTime: $O(|T|^n)$
 - Query complexity: ExpTime: O(n^|Q|)
 - Combined complexity: ExpTime: O(|In|^|In|)
- MSO: data is linear, query is PSpace

Data complexity of XPath

- Unary NavXPath has linear data complexity
 - Proof: boolean MSO is linear on trees
- MSO does not help much with combined complexity:
 - MSO over trees is PSpace-complete for combined complexity

Combined complexity

- · NavXPath is PTime-hard
- Full XPath 1.0 is in O(|Data|^5 * |Query|^2)

Satisfiability

- · FO over trees is decidable, but is non-elementary
- Satisfiability for NavXPath and for unnested NavXPath is ExpTime complete:
 - Reduction to Deterministic Propositional Dynamic Logic with Converse shows that NavXPath is in ExpTime (Marx EDBT 04)
 - Hardness follows by hardness of containmens (Neven-Schwentick – ICDT 03)
 - An O(2ⁿ) algorithm has been recently described, based on translation on mu-calculus with converse
- Satisfiability for NavXPath with intersection is NExpTime complete
 - Etessami Vardi Wilke: FO2 can encode Unary Temporal Logic

XPath fragments

- P-NavXPath: no negation, and = is the only relation
- Benedikt Fan Geerte (PODS05:
 - PNavXPath with downard axes: every expression is satisfiable
 - If we add upward, or sibling, or a DTD: NP-complete
 - P-FOXPath is still NP-complete
- · However (Geerts-Fan, DBPL05):
 - Sat for FOXPath is undecidable
 - Reduction from halting of two-register machines
- · Borders of decidability are not well understood