

# Footprint property

# Footprint recipe

#### Given a command r

- 1. Derive the specification of r using local axioms
- 2. Apply rule frame to complete the specification

```
\{P * x \mapsto \_\}
\{x \mapsto \_\}
[x] := 1;
\{x \mapsto 1\}
a := [x]
\{x \mapsto 1 \land a = 1\}
\{P * x \mapsto 1 \land a = 1\}
```

# Footprint fails in SL

#### Counterexample:

We would like to derive

```
\{y \mapsto \bot\} \ x := alloc(); free(x) \{y \mapsto \bot \land y \neq x\}
```

#### Information loss

```
\{x \mapsto \_\} [x] := y \{x \mapsto y\} // \text{write}
\{y \mapsto v\} \ x := [y] \ \{x = v \land y \mapsto v\} \ // \text{ read}
                                                                   resources can grow
   \{emp\} x := alloc() \{x \mapsto \_\} // alloc
\{x \mapsto \_\} free(x) {emp} // dispose
```

# Incorrectness Separation Logic (ISL)



#### Local Reasoning About the Presence of Bugs: Incorrectness Separation Logic

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**Abstract.** There has been a large body of work on local reasoning for proving the *absence* of bugs, but none for proving their *presence*. We present a new formal framework for local reasoning about the presence of bugs, building on two complementary foundations: 1) separation logic and 2) incorrectness logic. We explore the theory of this new *incorrectness separation logic* (ISL), and use it to derive a begin-anywhere, intra-procedural symbolic execution analysis that has no false positives *by construction*. In so doing, we take a step towards transferring modular, scalable techniques from the world of program verification to bug catching.

**Keywords:** Program logics · Separation logic · Bug catching

#### 1 Introduction

There has been significant research on sound, local reasoning about the state for proving the absence of bugs (e.g., [2,13,26,29,30,41]). Locality leads to techniques that are compositional *both* in code (concentrating on a program component) and in the resources accessed (spatial locality), without tracking the entire global state or the global program within which a component sits. Compositionality enables reasoning to scale to large teams and codebases: reasoning can be done even when a global program is not present (e.g., a library, or during program construction), without having to write the analogue of a test or verification harness, and the results of reasoning about components can be composed efficiently [11].

Meanwhile, many of the practical applications of symbolic reasoning have aimed at proving the *presence* of bugs (i.e., bug catching), rather than proving their absence (i.e., correctness). Logical bug catching methods include symbolic model checking [7,12] and symbolic execution for testing [9]. These methods are usually formulated as global analyses; but, the rationale of local reasoning holds just as well for bug catching as it does for correctness: it has the potential to

### CAV 2020

"bugs are a fundamental enough phenomenon to warrant a fundamental compositional theory for reasoning positively about their existence"













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## ISL = IL + SL

```
SL
                                 \{P\} r \{Q\}
[P]r[\epsilon:Q]
                             \{P*R\} r \{Q*R\}
          ISL
               [P] r [\epsilon : Q]
         [P*R]r[\epsilon:Q*R]
```

# Regular commands

```
e := skip
 regular
                              atomic
command
                             command
                                                                      simplified
                                     choice
                      r_1; r_2
                                                   [x] := y' // write
                                                    x := alloc()
                                                    free(x)
error()
                                                                        can fail
                             Kleene
                              star
```

## Disclaim

for the sake of presentation, some technical aspects are not fully detailed



#### Local axioms: write

$$\mathsf{SL}\left[\overline{\{x\mapsto \_\}\ [x] := y\ \{x\mapsto y\}}\right]$$

```
[x \mapsto v] [x] := y [ok : x \mapsto y]
must put a value
```

$$[x = nil] [x] := y [er : x = nil]$$

null pointer dereference

#### Local axioms: read

$$\mathsf{SL}\left[\overline{\{y\mapsto v\}\,x:=[y]\,\{x=v\wedge y\mapsto v\}}\right]$$

$$[y \mapsto v] x := [y] [ok : x = v \land y \mapsto v]$$

$$[y = nil] x := [y] [er : y = nil]$$

null pointer dereference

#### Local axioms: allocation

$$SL \quad \overline{\{emp\} \ x := alloc() \ \{x \mapsto \_\}}$$

```
[x \doteq x'] \ x := alloc() \ [ok : x \mapsto \_]
needed for footprint
```

# Local axioms: dispose (1st try)

```
SL \left( \frac{}{\{x \mapsto \_\} \text{ free}(x) \{emp\}} \right)
```

```
[x \mapsto v] free(x) [ok : emp]

must put a value
```

```
[x = nil] free(x) [er: x = nil]
```

null pointer dereference

#### Unsound Frame rule

$$[P] r [\epsilon : Q]$$

$$[P*R] r [\epsilon : Q*R]$$

#### Solution

**Boolean and** 

classical

assertions

assertion

```
P := true | false | a_1 < a_2 | a_1 = a_2 | ...
    \neg P \mid P_1 \land P_2 \mid \exists x . P \mid ...
         emp
                                       structural
     P_1 * P_2
                                       assertions
                 track deallocated
```

locations

### Satisfaction: structural

```
\langle s, h \rangle \models a_1 \mapsto a_2 iff dom(h) = \{ [[a_1]]s \} and h([[a_1]]s) = [[a_2]]s
\langle s, h \rangle F emp iff h is the empty map []
\langle s,h\rangle \models P_1 * P_2 iff \exists h_1,h_2. \langle s,h_1\rangle \models P_1 and \langle s,h_2\rangle \models P_2 and h=h_1 \bullet h_2
                              iff dom(h) = \{s(x)\} and h(s(x)) = \bot
\langle s, h \rangle \models x \not\mapsto
```

Notably:  $x \mapsto v * x \not\mapsto \equiv \text{false} \equiv x \not\mapsto * x \not\mapsto$ 

 $y \mapsto v * x \not\mapsto \equiv y \mapsto v * x \not\mapsto \land x \neq y$ 

# Local axioms: dispose

 $SL \left( \overline{\{x \mapsto \_\} \text{ free}(x) \{emp\}} \right)$ 

```
[x \mapsto v] \text{ free}(x) [ok : x \mapsto]
\text{must put a } \text{ track deallocated locations}
\text{this way resources } \text{ cannot shrink}
```

```
[x = nil] free(x) [er : x = nil]

null pointer dereference
```

## Example

```
\frac{[x \mapsto v] \text{ free}(x) [\text{ok} : x \not\mapsto]}{[x \mapsto v * x \mapsto v] \text{ free}(x) [\text{ok} : x \not\mapsto * x \mapsto v]} [\text{frame}] \\
\frac{[\text{false}] \text{ free}(x) [\text{ok} : false]}{[\text{cons}]} [\text{frame}]
```

# Footprint holds in ISL

We would like to derive

$$[y \mapsto \_] x := alloc(); free(x) [ok : y \mapsto \_ \land x \not\mapsto \land y \neq x]$$

```
[y \mapsto \_*emp]
[emp]
x := alloc();
[x \mapsto v]
free(x)
[x \not\mapsto]
[ok : y \mapsto \_*x \not\mapsto \land y \neq x]
```

#### Additional local axioms

```
[x \mapsto ][x] := y [er : x \mapsto ]
                                                     use after free
                                                        errors
y \not\mapsto x := [y] [er : y \not\mapsto ]
                                                   double free
x \mapsto free(x) [er : x \mapsto ]
                                                      error
                                                                             reuse of
[y \not\mapsto ]x := alloc() [ok : x \mapsto v \land x = y]
                                                                            deallocated
                                                                             locations
```

# Soundness and completeness

#### Relational semantics

```
[\![ skip ]\!] ok \triangleq \{(\sigma, \sigma)\}
                                                                                                                                                                              [skip]er \triangleq \emptyset
[b] ] ok \triangleq \{(\sigma, \sigma) \mid \sigma = \langle s, h \rangle \land s \models b\}
                                                                                                                                                                                 [b?]er \triangleq \emptyset
[[x := a]] \circ \mathsf{k} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto [[a]]s], h \rangle)\}
                                                                                                                                                                         [x := a] = \emptyset
[[error()]]ok \triangleq \emptyset
                                                                                                                                                          [[error()]] er \triangleq \{(\sigma, \sigma)\}
[[x := [y]]] \circ \mathsf{k} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto v], h \rangle) \mid v = h(s(y)) \in \mathbb{Z}\}
                                                                            [x := [y]] = \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(y) = \text{nil} \lor h(s(y)) = \bot \}
[[x] := y] \circ \mathsf{k} \triangleq \{(\langle s, h \rangle, \langle s, h[s(x) \mapsto s(y)] \rangle) \mid h(s(x)) \in \mathbb{Z}\}
                                                                             \llbracket[x] := y \rrbracket \text{er} \triangleq \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(x) = \text{nil} \lor h(s(x)) = \bot \}
[[x := \mathsf{alloc}()]] \circ \mathsf{k} \triangleq \{(\langle s, h \rangle, \langle s[x \mapsto n], h[n \mapsto v] \rangle) \mid v \in \mathbb{Z} \land (n \notin \mathsf{dom}(h) \lor h(n) = \bot)\}
                                                                                                                                                              [x := alloc()] = \emptyset
[\![\mathsf{free}(x)]\!]\mathsf{ok} \triangleq \{(\langle s, h \bullet [s(x) \mapsto v] \rangle, \langle s, h \bullet [s(x) \mapsto \bot] \rangle) \mid s(x) \in \mathbb{N} \land v \in \mathbb{Z}\}
                                                                           [[free(x)]]er \triangleq \{(\langle s, h \rangle, \langle s, h \rangle) \mid s(x) = nil \lor h(s(x)) = \bot \}
```

### Actual ISL rules

```
SKIP
                                                       Assign
                                                                                                                               HAVOC
                                                     \vdash [x=x'] x := e [ok:x=e[x'/x]]
                                                                                                                            \vdash [x=x'] x := * [ok : x=v]
\vdash [emp] skip [ok:emp]
         Assume
                                                                                                              Error
        \vdash [emp] assume(B) [ok:B]
                                                                                                            \vdash [emp] L: error [er(L): emp]
     SEQ1
                                                              Seq2
                                                                                                                                                Loop1
     \frac{\vdash [p] \ \mathbb{C}_1 \ [er(L):q]}{\vdash [p] \ \mathbb{C}_1; \mathbb{C}_2 \ [er(L):q]} \qquad \frac{\vdash [p] \ \mathbb{C}_1 \ [ok:r] \qquad \vdash [r] \ \mathbb{C}_2 \ [\epsilon:q]}{\vdash [p] \ \mathbb{C}_1; \mathbb{C}_2 \ [\epsilon:q]}
                                                                                                                                               \vdash [p] \mathbb{C}^* [ok : p]
CHOICE
CHOICE EXIST LOOP2
\vdash [p] \mathbb{C}_i [\epsilon : q] \quad \text{for some } i \in \{1, 2\} \qquad \vdash [p] \mathbb{C} [\epsilon : q] \quad x \notin \mathsf{fv}(\mathbb{C}) \qquad \vdash [p] \mathbb{C}^*; \mathbb{C} [\epsilon : q]
                                                                                    \vdash [\exists x.p] \ \mathbb{C} \ [\epsilon : \exists x.q]
                \vdash [p] \mathbb{C}_1 + \mathbb{C}_2 [\epsilon : q]
 Cons
                      \vdash [p'] \ \mathbb{C} \ [\epsilon : q'] \qquad q \Rightarrow q' \qquad \qquad \vdash [p_1] \ \mathbb{C} \ [\epsilon : q_1] \qquad \vdash [p_2] \ \mathbb{C} \ [\epsilon : q_2]
 p' \Rightarrow p
                                                                                                                    \vdash [p_1 \lor p_2] \mathbb{C} [\epsilon : q_1 \lor q_2]
                            \vdash [p] \mathbb{C} [\epsilon : q]
   Subst
                                                                                                         Local
                                                                                                                               \vdash [p] \mathbb{C} [\epsilon : q]
   \vdash [p] \ \mathbb{C} \ [\epsilon : q] \qquad y \not\in \mathsf{fv}(p, \mathbb{C}, q)
      \vdash [p[y/x]] \mathbb{C}[y/x] [\epsilon : q[y/x]]
                                                                                                         \vdash [\exists x. p] \text{ local } x \text{ in } \mathbb{C} [\epsilon : \exists x. q]
```

```
FRAME
                                                                                           Alloc1
 \vdash [p] \ \mathbb{C} \ [\epsilon:q] \qquad \mathsf{mod}(\mathbb{C}) \cap \mathsf{fv}(r) = \emptyset
                                                                                           \vdash [x=x'] \ x := \texttt{alloc()} \ [ok : x \mapsto -]
               \vdash [p*r] \mathbb{C} [\epsilon:q*r]
 FREE
                                                                  Alloc2
 \vdash [x \mapsto e] \text{ L:free(}x\text{)} [ok: x \not\mapsto ] \qquad \vdash [x=x'*y \not\mapsto ] x := alloc() [ok: x=y*y \mapsto -]
FREEER
                                                                                   FREENULL
\vdash [x \not\mapsto] \text{ L:free}(x) [er(L): x \not\mapsto]
                                                                                   \vdash [x=\text{null}] \text{ L:free}(x) [er(L): x=\text{null}]
Load
\vdash \begin{bmatrix} x = x' * y \mapsto e \end{bmatrix} \text{ L: } x := [y] \begin{bmatrix} ok : x = e[x'/x] * y \mapsto e[x'/x] \end{bmatrix} \qquad \vdash [x \mapsto e] \text{ L: } [x] := y \begin{bmatrix} ok : x \mapsto y \end{bmatrix}
LOADER
                                                                                               STOREER
\vdash [y \not\mapsto] \text{ L: } x := [y] [er(L) : y \not\mapsto]
                                                                                               \vdash [x \not\mapsto ] L: [x] := y [er(L): x \not\mapsto ]
LOADNULL
                                                                                     STORENULL
```

 $\vdash [x=\text{null}] \text{ L: } [x] := y [er(L): x=\text{null}]$ 

 $\vdash [y=\text{null}] \text{ L: } x := [y] [er(\text{L}): y=\text{null}]$ 

#### Correctness

Th. [correctness]

If [P] r  $[\epsilon:Q]$  then  $Q \subseteq [r]$   $\epsilon P$ 

Proof. By induction on the derivation.

# Footprint theorem

Th. [footprint]

Any valid ISL triple  $[\sigma_P]$  r  $[\epsilon:\sigma_Q]$  can be derived

Proof. See CAV2020 paper for details.

## Final considerations on SL

ISL = IL + SL for bug catching!

ISL address compositional bug catching

targets memory safety bugs (use-after-free)

no-false-positives theorem: all bugs are true

# Questions

### Question 1

Is the axiom  $[x \mapsto \_][x] := y[ok : x \mapsto y]$  sound?

$$(x \mapsto v) \Rightarrow (x \mapsto \_) \quad [x \mapsto v] [x] := y [ok : x \mapsto y]$$
$$[x \mapsto \_] [x] := y [ok : x \mapsto y]$$

#### Question 2

Prove that rule [\*conj] is unsound 
$$\frac{[P_1] \ r \ [Q_1]}{[P_1 * P_2] \ r \ [Q_1 * Q_2]} [*conj]$$

```
Consider x = 0 \ x := 1 \ x = 1 \ \text{and} \ x = 1 \ x := 1 \ x = 1
By rule [*conj] we could derive [false] x := 1 [x = 1]
which is not sound!
```

#### \* Exam 15

Can we derive the following ISL triple?

```
[x \mapsto 1] free(x); x := alloc() [ok : x \mapsto 2]
```